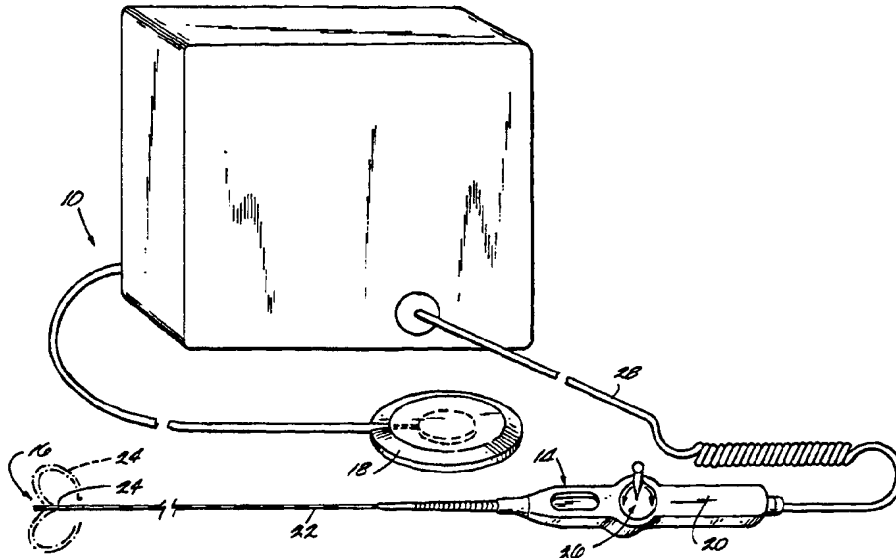




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(54) Title: TISSUE HEATING AND ABLATION SYSTEMS AND METHODS WHICH PREDICT MAXIMUM TISSUE TEMPERATURE



(57) Abstract

This invention is systems and methods to heat or ablate body or ablation energy to a tissue region. The systems and methods measure a first temperature using a temperature sensing element associated with the electrode (16). The systems and methods also measure a second temperature using a temperature sensing element associated with the electrode (16). The systems and methods process at least one of the first and second temperatures to derive a prediction of maximum temperature of the tissue region. The systems and methods generate an output that controls the transmission of the heating or ablation energy based, at least in part, upon the maximum tissue temperature prediction.

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**TISSUE HEATING AND ABLATION SYSTEMS
AND METHODS WHICH PREDICT MAXIMUM TISSUE
TEMPERATURE**

Field of the Invention

5 In a general sense, the invention is directed to systems and methods for creating lesions in the interior regions of the human body. In a more particular sense, the invention is directed to systems and methods for ablating heart tissue for
10 treating cardiac conditions.

Background of the Invention

 Physicians frequently make use of catheters today in medical procedures to gain access into interior regions of the body. In some procedures,
15 the catheter carries an energy transmitting element on its distal tip to ablate body tissues.

 In such procedures, the physician must establish stable and uniform contact between the energy transmitting element and the tissue to be
20 ablated. Upon establishing contact, the physician must then carefully apply ablating energy to the element for transmission to the tissue.

 The need for precise control over the transmission of ablation energy is especially
25 critical during catheter-based procedures for ablating heart tissue. These procedures, called electrophysiology therapy, are becoming increasingly more widespread for treating cardiac rhythm disturbances, called arrhythmias. Cardiac ablation
30 procedures typically use radio frequency (RF) energy

to form a lesion in heart tissue.

The principal objective of the invention is to provide systems and methods for monitoring and reliably controlling the application of energy to ablate body tissue, thereby providing therapeutic results in a consistent and predictable fashion.

Summary of the Invention

The invention provides systems and methods that provide reliable control over tissue heating and ablation procedures using temperature sensing.

Other features and advantages of the inventions are set forth in the following Description and Drawings, as well as in the appended claims.

Brief Description of the Drawings

Fig. 1 is a perspective view of a system for ablating tissue that comprises an energy emitting electrode and associated energy generator;

Figs. 2, 3 and 4 are, respectively, an elevated side view, an end view, and a side section view (taken along line 4-4 in Fig. 3) of the electrode associated with the system shown in Fig. 1, the electrode having two temperature sensing elements;

Fig. 5 is a schematic view of the generator for supplying energy to the electrode in the system shown in Fig. 1, the generator using a specialized modified PID control technique to maintain a desired set temperature by altering power in response to a prediction of maximum tissue temperature;

Fig. 6 is a schematic view of a device used to experimentally determine the relationship between maximum tissue temperature and the temperatures sensed by two sensing elements carried by an electrode;

Fig. 7A is a graph presenting a comparison, for an electrode-tissue angle of 90° , of the temperature variations with time when the actual highest tissue temperature controlled the application of radio frequency energy compared when a predicted maximum tissue temperature, calculated according to the invention, was used as the control input;

Fig. 7B is a graph presenting a comparison of applied power versus time under the same conditions set forth in Fig. 7A;

Fig. 8A is a graph presenting a comparison, for an electrode-tissue angle of 0° , of the temperature variations with time when the actual highest tissue temperature controlled the application of radio frequency energy compared when a predicted maximum tissue temperature, calculated according to the invention, was used as the control input;

Fig. 8B is a graph presenting a comparison of applied power versus time under the same conditions set forth in Fig. 8A;

Fig. 9 is a schematic view of the implementation of a neural network predictor to predict maximum tissue temperature;

Fig. 10 is a representative single-perception network that can be used to predict maximum tissue temperature according to the invention;

Fig. 11 is a graph presenting a comparison, for an electrode-tissue angle of 90° , of the temperature variations with time when the actual highest tissue temperature controlled the application of radio frequency energy compared when the predicted maximum tissue temperature output of

the network shown in Fig. 10 was used as the control input;

Fig. 12 is a schematic view of the implementation of fuzzy logic to predict maximum tissue temperature; and

Fig. 13 is a flexible, multiple electrode element with multiple temperature sensing elements that can be used to predict maximum tissue temperature according to the invention;

Fig. 14 is an electrode with multiple temperature sensing elements, and a heating element to heat the electrode, which can be used to predict maximum tissue temperature according to the invention;

Fig. 15 is an alternative embodiment of an electrode with multiple temperature sensing elements and a heating element which can be used to predict maximum tissue temperature according to the invention;

Fig. 16 is a system including an electrode like that shown in either Fig. 14 or Fig. 15, which can be used to predict maximum tissue temperature according to the invention; and

Figs. 17 and 18 are schematic views of a system for controlling the application of ablation energy to multiple electrodes using multiple predicted maximum tissue temperature inputs.

The invention may be embodied in several forms without departing from its spirit or essential characteristics. The scope of the invention is defined in the appended claims, rather than in the specific description preceding them. All embodiments that fall within the meaning and range of equivalency of the claims are therefore intended to be embraced by the claims.

Description of the Preferred Embodiments

Fig. 1 shows a system 10 for ablating human tissue that embodies the features of the invention.

5 In the illustrated and preferred embodiment, the system 10 includes a generator 12 that delivers radio frequency energy to ablate tissue. Of course, other types of energy can be generated for tissue ablating purposes.

10 The system 10 also includes a steerable catheter 14 carrying a radio frequency transmitting ablation electrode 16. In the illustrated embodiment, the ablation electrode 16 is made of platinum.

15 In the illustrated embodiment, the system 10 operates in a unipolar mode. In this arrangement, the system 10 includes a skin patch electrode that serves as an indifferent second electrode 18. In use, the indifferent electrode 18 attaches to the patient's back or other exterior skin area.

20 Alternatively, the system 10 can be operated in a bipolar mode. In this mode, the catheter 14 carries both electrodes.

25 The system 10 can be used in many different environments. This specification describes the system 10 when used to provide cardiac ablation therapy.

30 When used for this purpose, a physician steers the catheter 14 through a main vein or artery (typically the femoral vein or artery) into the interior region of the heart that is to be treated. The physician then further manipulates the catheter 14 to place the electrode 16 into contact with the tissue within the heart that is targeted for
35 ablation. The user directs radio frequency energy

from the generator 12 into the electrode 16 to ablate and form a lesion on the contacted tissue.

In the embodiment shown in Fig. 1, the catheter 14 includes a handle 20, a catheter body 22, and a distal tip 24, which carries the electrode 16.

The handle 20 encloses a steering mechanism 26 for the catheter tip 24. A cable 28 extending from the rear of the handle 20 to connect the catheter 14 to the generator 12 for conveying radio frequency energy to the ablation electrode 16 via a signal wire 29 (see Fig. 4).

Left and right steering wires 54 (see Fig. 4) are connected to a steering spring 52 at the tip of the catheter body 22. The steering wires extend through the catheter body 22 to interconnect the steering mechanism 26 in the handle 20 (see Fig. 1). Rotating the steering mechanism 26 to the left pulls on the left steering wire, causing the spring 52 and tip 24 to bend to the left. In the same way, rotating the steering mechanism 26 to the right causes the spring 52 and tip 24 to bend to the right. In this way, the physician steers the ablation electrode 16 into contact with the tissue to be ablated.

Further details of this and other types of steering mechanisms for the ablating element 10 are shown in Lunquist and Thompson U.S. Patent 5,254,088, which is incorporated into this Specification by reference.

I. Multiple Temperature Sensing

As Figs. 2 to 4 show, the ablation electrode 16 carries two temperature sensing elements 30 and 32. As will be described in greater detail later, the power that the generator 12

applies to the electrode 16 is set, at least in part, by the temperature conditions sensed by the elements 30 and 32.

5 As best shown Figs. 3 and 4, the ablation electrode 16 includes an interior well 34 extending through its center. The two temperature sensing elements 30 and 32 occupy this well 34.

10 In the illustrated embodiment, the first temperature sensing element 30 is carried within a cap 42 at the distal extremity of the well 34. In use, the sensing element 30 is intended to make thermal conductive contact with tissue, to thereby sense tissue temperature.

15 Lead wires 38 extend from the sensing element 30 through the catheter body 22 into the catheter handle 20. There, the lead wires 38 electrically couple to the cable 28 for connection to the generator 12. The lead wires 38 transmit the tissue temperature signals from the temperature
20 sensing element 30 to the generator 12.

In the illustrated and preferred embodiment, the sensing element 30 comprises a conventional small bead thermistor 40. For example, a 0.55 mm bead thermistor commercially available
25 from Thermometrics (Edison, New Jersey), Part Number AB6B2-GC16KA143E/37° C-A can be used.

The sensing element 30 and lead wires 38 are electrically insulated from the surrounding ablation electrode 16. For this purpose,
30 electrically insulating potting compound, such as heavy isomid, cyanoacrylate adhesive, silicon rubber RTV adhesive, polyurethane, epoxy, or the like, encapsulates the thermistor bead 40 in conventional fashion. The lead wires 38 are likewise enclosed in
35 electrically insulating sheaths made from, for

example, polyimide material, although other conventional electrical insulating materials also can be used.

5 The cap 42 is made from a thermal
conducting material having a high thermal
conductivity that is at least 1.0 watt (W) per meter
(m) Kelvin (K), or 1.0 W/m K. Metallic materials
like stainless steel, gold, silver alloy, platinum,
10 copper, nickel, titanium, aluminum, and compositions
containing stainless steel, gold, silver, platinum,
copper, nickel, titanium, and aluminum possess this
degree of thermal conductivity. The encapsulated
thermistor bead 40 is preferably potted within the
15 cap 42 using an electrically insulating epoxy having
an enhanced thermal conductivity that is at least
1.0 W/m K. The inclusion of a metallic paste (for
example, containing aluminum oxide) in a standard
epoxy material will provide this enhanced thermal
conductivity.

20 The cap 42 is fitted within the well 34 of
the electrode 16 with its distal end 44 making
thermal conductive contact with the tissue. The high
thermal conductivity of the cap material assures
that the cap 42 will quickly reach an equilibrium
25 temperature close to that of the tissue it contacts.

 In the illustrated and preferred
embodiment, a thermal and electrically insulating
barrier 46 forms an interface between the interior
wall of the well 34 and the side of the cap 42 that
30 occupies it. In a preferred embodiment, the barrier
46 comprises polyamide adhered about the sidewall of
the cap 42 using FMD-14 to serve as an electrical
insulator. The barrier 46 also comprises polyester
shrink tubing secured by heat shrinking about the
35 polyamide to serve as a thermal insulator. In the

illustrated and preferred embodiment, the thermistor-containing cap 42 and associated barrier 46 are affixed and potted within the electrode well using cyanoacrylate FMD-13 (Loctite Corporation, Newington, Connecticut).

The thermal conducting cap 42 creates an isothermal condition about the sensing element 30 close to the actual temperature of the tissue it contacts. Furthermore, the cap 42, being substantially isolated from thermal conductive contact with the electrode 16, retains this isothermal condition about sensing element 30, preventing its dissipation by the thermal mass of the electrode 16. Further details of the use and construction of the thermal conducting cap 42 are found in copending U.S. Patent Application Serial No. 08/432,321, filed May 1, 1995, and entitled "Systems and Apparatus for Sensing Temperature in Body Tissue", which is incorporated herein by reference.

The second temperature sensing element 32 carried within the well 34 is connected by soldering or by thermal conductive adhesive in direct thermal conductive contact with the thermal mass of the electrode 16. While transmitting radio-frequency energy to heat surrounding tissue, the electrode 16 is heated by thermal conduction from the heated tissue. In use, the second sensing element 32 is intended to sense the temperature of the electrode 16 due to conductive heat transfer.

In the illustrated and preferred embodiment, the sensing element 32 also comprises a conventional small bead thermistor 48, as already described in connection with the sensing element 30. Also, like the sensing element 30, the sensing

element 32 is electrically insulated from the electrode 16 by encapsulation in an electrically insulating potting compound, as also already described.

5 The thermistor 48 also has associated lead wires 50, which extend through the catheter body 22 and handle 20 to the cable 28. The cable 28 transmits the electrode temperature signals from the temperature sensing element 32 to the generator 12.

10 It should be appreciated that the first temperature sensing element 30 need not be positioned in thermal conductive contact with tissue. The first element 30 can, like the second element 32, be positioned in thermal conductive
15 contact with the electrode 16. It is also not necessary that one or both sensing elements 30 and 32 be in direct thermal conductive contact with the electrode 16. The invention requires only that the two temperature sensing elements 30 and 32 be
20 positioned relative to the electrode 16 in a spaced apart condition to measure a meaningful spatial temperature gradient at the tissue-electrode interface.

 It should also be appreciated that the
25 electrode 16 need not be in direct contact with tissue. Laser and microwave transmitting electrodes can carry the spaced apart temperature sensing elements 30 and 32 and perform tissue ablation according to invention without contacting the
30 ablated tissue.

 The apparatus and methods that embody the features of the invention are well suited for use in the field of cardiac ablation, which the preferred embodiments exemplify. Still, the invention is
35 applicable for use in tissue heating applications,

as well. For example, the various aspects of the invention have application in procedures for ablating or heating tissue in the prostate, brain, gall bladder, uterus, and other regions of the body, using systems that are not necessarily catheter-based.

It should be appreciated that other types of temperature sensing elements can also be used. For example, a thermocouple could be used as the temperature sensing element. In a preferred implementation, the thermocouples are constructed by either spot welding or by laser stripping and welding the different metals together to form the thermocouple junction. When a thermocouple serves as the temperature sensing element, a reference thermocouple must be used. The reference thermocouple may be placed in the handle 20, generator 12, or exposed to the blood pool in the manner disclosed in copending U.S. Patent Application Serial No. 08/286,937, filed August 8, 1994, and entitled "Systems and Methods for Sensing Temperature Within the Body."

Electrical insulation is also required when thermocouples are used as the temperature sensors. For example, the thermocouple junction can be placed in a thermally conducting epoxy inside a polyester sleeve. In a preferred implementation, the thermocouple junction is placed in UV modified acrylic adhesive 330 (Loctite Corporation, Newington, Connecticut) within a shrink polyester sleeve, which is then shrunk to fit tightly about the thermocouple junction and wires. To reduce electrical interference, the thermocouple wires are also preferably electrically shielded and twisted together.

II. THE RF GENERATOR

As Fig. 5 shows, the generator 12 includes a radio frequency power source 56 connected through a main isolation transformer 58 to outlet and return lines 60 and 62. Outlet line 60 leads to the ablation electrode 16. Return line 62 leads from the indifferent electrode 18.

In the illustrated embodiment, when used for cardiac ablation, the power source 56 is typically conditioned to deliver up to 150 watts of power at a radio frequency of 500 kHz.

The generator 12 further includes a temperature acquisition system 64, a temperature processing element 66, a demand power processor 68, and a converter 70. These components comprise a feedback loop, which couples the two temperature sensing elements 30 and 32 to the source 56 for making applied radio-frequency energy responsive to sensed temperature conditions.

The temperature acquisition system 64 is coupled to the two temperature sensing elements 30 and 32. The system 64 continuously samples at prescribed time periods, t , the analog signals generated by the sensing elements 30 and 32 based upon sensed temperature conditions. The system 64 converts the separate analog signals of the sensing elements 30 and 32 into individual, proportional digital signals, respectively tissue temperature $T_1(t)$ and electrode temperature $T_2(t)$.

The temperature processing element 66 is coupled to the temperature acquisition system 64 to receive as input the digital signals tissue temperature $T_1(t)$ and electrode temperature $T_2(t)$. The processing element 66 applies prescribed criteria to these actual temperature signals to

derive, for the sampled time interval, a prediction of the hottest tissue temperature present in the tissue region in the vicinity of the electrode 16, $T_{pred}(t)$.

5 The demand power processor 68 periodically compares $T_{pred}(t)$ to a set temperature value T_{set} . The set temperature value T_{SET} can be inputted by the physician through an interface 72. The set temperature value T_{SET} represents the maximum tissue
10 temperature the physician wants to maintain at the ablation site. The value T_{SET} can be established in other ways. For example, the value T_{SET} can vary over time to define a set temperature curve.

 The set temperature value T_{SET} selected
15 depends upon the desired therapeutic characteristics of the lesion. Typical therapeutic lesion characteristics are the surface area of the tissue that is ablated and depth of the ablation. Typically, the set temperature T_{SET} is in the range of 50 to 90
20 degrees C.

 Based upon this comparison, and preferably taking into account the magnitude of the instantaneous power $P(t)$ supplied to the ablating electrode 16, the processor 68 derives the demand
25 power output $P_{DEMAND}(t)$. The demand power output $P_{DEMAND}(t)$ represents the magnitude of the radio frequency power that should be supplied to the ablating electrode 16 to establish or maintain the desired local temperature condition T_{SET} at the
30 ablating electrode 16. By taking into account the magnitude of the instantaneous power $P(t)$, the processor 68 assures that a prescribed maximum power level P_{MAX} is not exceeded.

 The manner in which the processor 68
35 derives $P_{DEMAND}(t)$ can vary. For example, it can

employ proportional control principles, proportional integral derivative (PID) control principles, adaptive control, neural network, and fuzzy logic control principles.

5

EXAMPLE 1

The following Example 1 shows an exemplary core PID control algorithm that the processor 68 can employ for controlling power based upon predicted tissue temperature.

10

In this example, K_p , K_d , and K_i are, respectively, the proportional, derivative, and integral coefficients of the PID algorithm used for controlling power based on predicted tissue temperature. The same algorithm was used to control actual tissue temperature in the comparisons presented in Figs. 7 A/B and 8 A/B, to be discussed in greater detail later.

15

In this algorithm, the power at time $t+1$ is controlled based upon the difference between the temperature and the set temperature at times t , $t-1$, and $t-2$ (expressed in Kelvin or degrees Celsius), as follows:

20

$$\text{power}(t+1) = 7W * \{ K_p * (T(t) - T_{\text{SET}}) + K_d * [(T(t) - T_{\text{SET}}) - (T(t-1) - T_{\text{SET}})] + K_i * [(T(t) - T_{\text{SET}}) + (T(t-1) - T_{\text{SET}}) + (T(t-2) - T_{\text{SET}})] \}$$

25

Data collected from the finite element analysis presented below (in Section III(A)) demonstrates that the following coefficients can be used:

30

$$K_p = 0.04$$

$$K_i = 0.005$$

$$K_d = 0.008$$

The multiplier "7W" appearing in the above algorithm reflects that the finite element analysis,

35

from which the coefficients were derived, computed the power-to-temperature transfer function of the modeled system at a 7 watt (W) level.

5 The foregoing example sets forth the core of the control algorithm for deriving $p(I)$ (i.e., P_{Demand} , based upon a fixed value of T_{SET} . The algorithm can include other auxiliary features.

10 For example, T_{SET} can be expressed as a function with respect to time, which can be linear, or nonlinear, or both.

As another example, P_{Demand} derived by the algorithm can be compared to a maximum power condition. Should P_{Demand} exceed the maximum power condition, the controller 68 blocks passage of P_{Demand} and instead commands a preestablished low power condition until P_{Demand} becomes less than the maximum power.

20 Other representative implementations are disclosed in copending Patent Application Serial No. 08/266,934, filed June 27, 1994, and entitled "Tissue Heating and Ablation Systems and Methods Using Predicted Temperature for Monitoring and Control."

25 The converter 70 derives a command voltage signal $V_{\text{DEMAND}}(t)$ based upon the demand power output $P_{\text{DEMAND}}(t)$. The command voltage signal $V_{\text{DEMAND}}(t)$ adjusts the amplitude of the voltage $V_{(t)}$ supplied to the source 56 to thereby adjust $P_{(t)}$. Alternatively, the converter 70 could derive a command current signal

30 $I_{\text{DEMAND}(t)}$ based upon the demand power output $P_{\text{DEMAND}}(t)$ to adjust the amplitude of the current supplied to the source 56, achieving the same results.

The manner in which the converter 70 generates $V_{\text{DEMAND}}(t)$ to adjust $P(t)$ can vary. For

35 example, the converter 70 can employ proportional

control principles, proportional integral derivative (PID) control principles, neural network, fuzzy logic, and adaptive control principles. Representative implementations are disclosed in
5 copending Patent Application Serial No. 08/266,934, filed June 27, 1994, and entitled "Tissue Heating and Ablation Systems and Methods Using Predicted Temperature for Monitoring and Control."

III. Deriving T_{PRED} (t)

A. Prediction Based Upon An Analytical Function

The quantity T_{PRED} can be expressed in terms of an analytical function $f(T_1, T_2)$, which sets forth, for a given electrode geometry, the variation
15 of hottest tissue temperature T_{MAX} with sensed tissue temperature T_1 and sensed electrode temperature T_2 . The function is determined for a given electrode geometry by tabulating in vitro or in vivo results, measuring T_1 , T_2 , and T_{MAX} , and generating finite
20 element models for the same electrode geometries to estimate T_{PRED} , until the modeled $T_{\text{PRED}} \approx$ measured T_{MAX} .

EXAMPLE 2 (Determining an Analytical T_{PRED} Function)

A three-dimensional finite element model is created for an 8F diameter/5 mm long radio frequency
25 ablation electrode placed in a blood pool in contact with an approximately 4 cm thick rectangular slice of cardiac tissue at tissue-electrode angles of 0° and 90° . The electrode has two temperature sensing elements, as shown in Figs. 2 to 4, one electrically
30 and thermally isolated at the tip for sensing tissue temperature and the other electrically isolated but in thermal conductive contact with the electrode for sensing electrode temperature. The tip of the electrode extends about 1.3 mm into the tissue. The
35 overall volume is a parallelepiped 8 cm long, 4 cm

wide, and 4 cm thick. The model has 8144 nodes, using hexahedral elements and a nonuniform mesh.

The current density boundary conditions are set at the electrode, so that the maximum tissue temperature (T_{MAX}) reaches about 95° C after 120 seconds.

COSMOS is used on a Hewlett Packard workstation to perform the electrical-thermal, transient analyses for 120 seconds. The analyses estimate the function that defines the relationship between T_1 , T_2 , and the predicted maximal tissue temperature.

The model results are corroborated with experimental data acquired using the apparatus shown in Fig. 6. A 4 cm thick slice of bovine heart H is fixed in good contact with a 144 cm² patch electrode EP inside a tank T filled with saline at 37° C. An ablation catheter C carrying an 8F diameter/5 mm long electrode E is placed in contact with the tissue surface H at an angle of 0° and 90°. A 0.55 mm bead thermistor TM1 is placed at the electrode tip (to sense T_1), another 0.55 mm bead thermistor TM2 is placed within the electrode (to sense T_2), and a third thermistor TM3 is placed in the cardiac tissue H about .5 mm beneath the electrode tip, which corresponds to the hottest tissue temperature region predicted by the finite element simulations. The thermistor readings are acquired at a sampling rate of 20 ms by LabView running on a Power Mac. A 500 kHz sinusoidal signal is applied between the ablation and indifferent electrodes using a 150 W RF ablation system AS. The delivered RF power (P) is kept constant at 7 W.

Using the above-described methodology, the following function was determined to yield good

results for the 8F/5 mm electrode:

$$T_{\text{Pred}}(t) = 4.03 * T_1(t) - 2.97 * T_2(t)$$

The above-described methodology can be used to derive the function for other electrode geometries, as well.

The behavior of the function for an 8F/5 mm electrode is acceptable at both tissue-electrode angles of 0° and 90°. Fig. 7A presents a comparison, for an electrode-tissue angle of 90°, of the temperature variations with time when the actual highest tissue temperature controlled the application of radio frequency energy compared when T_{Pred} , calculated according to the above function, was used as the control input, using the PID control algorithm like that disclosed above. Fig. 7B presents a comparison of applied power versus time under the same conditions. Figs. 8A and 8B present similar comparisons for a tissue-electrode angle of 0°. Both comparisons show that any overshoot and settling time will, in time, converge to zero.

Since the data reflected in Figs. 7B and 8B are based upon a finite element analysis conducted at 7 W, the numbers on the y-axis shown in Figs. 7B and 8B should be multiplied by 7 W to obtain the true power levels.

Figs. 7B and 8B also show that keeping the temperature at a fixed set value requires a continuous, slow ramping down of applied power. This is because the temperature of heart tissue, when heated at a constant applied power, does not actually reach a steady state below 100° C. Instead, maximum tissue temperature is observed to continuously increase at a slow rate until it reaches 100° C, at which time micro-explosions occur. This rate is defined by the expression:

- 19 -

$$\frac{\partial T}{\partial t} = \frac{1}{\rho \cdot c} j \cdot E > 0$$

where:

T is tissue temperature.

t is time.

5 $\partial T / \partial t$ is the first temporal derivative
of the temperature.

ρ is tissue density.

c is heat capacity of the tissue.

j is current density.

E is electric field intensity.

10 As Figs. 7B and 8B show, there is, for a
given electrode geometry and electrode-tissue angle,
a determinable rate at which power decreases to
maintain a predicted maximum tissue temperature. In
Fig. 7B, the rate is 0.008 W/sec for an 8F/5 mm
15 electrode and a 90° tissue-electrode angle. In Fig.
8B, the rate is 0.003 W/sec for an 8F/5 mm electrode
and a 0° tissue-electrode angle. The temperature
processor 66 can ascertain this power-down rate upon
deriving $T_{\text{PRED}}(t)$ using preestablished look-up tables.
20 The processor 66 can generate the power-down rate as
output to the demand power processor 68, instead of
 $T_{\text{PRED}}(t)$. The processor 68 would control predicted
tissue temperature by ramping down the power
transmitted by the electrode based upon the power-
25 down rate.

B. Prediction Based Upon Neural Networks

The dependence of maximum tissue
temperature on T_1 and T_2 can also be approximated
using neural networks. Fig. 9 shows an
30 implementation of a neural network predictor 300,
which receives as input the temperatures $T_1(t)$ and
 $T_2(t)$ sensed at the electrode. The predictor 300

- 20 -

outputs a predicted temperature of the hottest tissue region $T_{\text{PRED}}(t)$.

5 The predictor 300 uses a two-layer neural network, although more or less hidden layers could be used. As shown in Fig. 9, the predictor 300 includes first and second hidden layers and four
10 neurons, designated $N(L,X)$, where L identifies the layer 1 or 2 and X identifies a neuron on that layer. The first layer ($L=1$) has three neurons ($X = 1$ to 3), as follows $N(1,1)$; $N(1,2)$; and $N(1,3)$. The second layer ($L=2$) comprising one output neuron ($X=1$), designated $N(2,1)$.

15 Temperature readings from the multiple sensing elements are weighed and inputted to each neuron $N(1,1)$; $N(1,2)$; and $N(1,3)$ of the first layer. Fig. 9 represents the weights as $W^L(k,N)$, where $L=1$; k is the input sensor order; and N is the input neuron number 1, 2, or 3 of the first layer.

20 The output neuron $N(2,1)$ of the second layer receives as inputs the weighted outputs of the neurons $N(1,1)$; $N(1,2)$; and $N(1,3)$. Fig. 9 represents the output weights as $W^L(O,X)$, where $L=2$; O is the output of neuron 1, 2, or 3 of the first layer; and X is the input neuron number of the
25 second layer. Based upon these weighted inputs, the output neuron $N(2,1)$ predicts $T_{\text{PRED}}(t)$. Alternatively, a sequence of past reading samples from each sensor could be used as input. By doing this, a history term would contribute to the prediction of the
30 hottest tissue temperature.

35 The predictor 300 must be trained on a known set of data containing the temperature of the sensing elements T_1 and T_2 and the temperature of the hottest region, which have been previously acquired experimentally in the manner set forth in the

foregoing example. For example, using a back-propagation model, the predictor 300 can be trained to predict the known hottest temperature of the data set with the least mean square error. Once the training phase is completed, the predictor 300 can be used to predict $T_{\text{PRED}}(t)$.

EXAMPLE 3: TISSUE TEMPERATURE PREDICTION USING NEURAL NETWORKS

Fig. 10 shows a single perceptron network 302 with inputs $T_{\text{TIP}}(t)$ and $T_{\text{CENTER}}(t)$ corresponding with temperatures sensed by sensing element 30 and sensing element 32, respectively. The output is $T_{\text{PRED}}(t)$. Weights w_1 and w_2 and bias $\theta(t)$ are used.

This network 302 computes $T_{\text{PRED}}(t)$ as follows:

$$\begin{aligned} u(t) &= w_1 * (T_{\text{TIP}}(t) - T_{\text{TIP}}(0)) + w_2 * (T_{\text{CENTER}}(t) - T_{\text{CENTER}}(0)) - \theta \\ y(t) &= 2 / (1 + \exp(-0.002 * u(t))) - 1 \\ T_{\text{PRED}}(t) &= 150 * y(t) + 37 \end{aligned}$$

The relationship between $y(t)$ and $u(t)$ is an activation function, which, in the above network 302, is a sigmoidal function. The factor "150" in the last equation is required because of the chosen activation function. The term "37" reflects the temperature of the tissue before ablation, i.e., body temperature. The coefficients are derived based on the experimental data presented above in Section III(A) with the apparatus shown in Fig. 6

The weights w_1 and w_2 and the bias term $\theta(t)$ were set based upon training on four experimental sets of data. During the training sessions, the weights and bias terms were updated using the back-propagation algorithm described in S. Haykin, "Neural Networks," IEEE Press (New York), 1994. The

final values were computed by averaging the results in the four training sessions.

Fig. 11 presents a comparison, for an electrode-tissue angle of 90° , of the temperature variations with time, at a constant power of 7 W, between actual and predicted maximal tissue temperature. The comparison was conducted after the training sessions and with data different than the data used for training, acquired using the apparatus shown in Fig. 6. The comparison shows good correspondence between the two control inputs, once overshoot and settling time converge to zero.

B. Prediction Based Upon Fuzzy Logic

The dependence of maximum tissue temperature on T_1 and T_2 can also be approximated using fuzzy logic. Fig. 12 shows an alternative embodiment of the temperature processor 66 which derives P_{DEMAND} using fuzzy logic control principles. In this implementation, the processor 66 includes a fuzzifier 502, which receives as inputs the temperature signals $T_1(t)$ and $T_2(t)$ from the sensing elements 30 and 32. The fuzzifier 502 also receives T_{SET} as input, either as a constant value or a value that changes over time. The fuzzifier 502 converts the pairs of $T_1(t)$ and $T_2(t)$ input data to fuzzy inputs based upon reference to T_{SET} on a relative basis. For example, the fuzzy inputs can determine the degree (or membership function) to which a given pair of $T_1(t)$ and $T_2(t)$ is, compared to T_{SET} , "cool" or "warm" or "warmer" or "hot".

These fuzzy inputs are passed through an I/O mapper 504 which converts them to fuzzy outputs by translating the inputs into descriptive labels of power. This is accomplished, for example, by using linguistic "if... then" rules, like "if the fuzzy

input is ... then the fuzzy output is" Alternatively, more complex mapping matrical operators can be used.

For example, if the $T_{1/2}$ pair is "cool," the I/O mapper 504 outputs the descriptive label "Largest Positive," to indicate that a large relative increase in power is required. By the same token, if the $T_{1/2}$ pair is "hot," the I/O mapper 504 outputs the descriptive label "Largest Negative," to indicate that large relative decrease in power is required. The intermediate fuzzy inputs "warm" and "warmer" produce intermediate descriptive labels as fuzzy outputs, such as "Smallest Positive" and "Smallest Negative."

These fuzzy outputs are passed through a defuzzifier 506. The defuzzifier 506 also receives actual power $P(t)$ as an input, since the fuzzy outputs refer to variations in $P(t)$. Based upon $P(t)$ and the variations required based upon the fuzzy outputs, the defuzzifier 506 derives $P_{\text{DEMAND}}(t)$.

To define proper reference sets and the rules of the I/O mapper 504, it may be required that the fuzzy logic controller be trained on a known set of data before use.

IV. Other Temperature Sensing Embodiments

A. Multiple Electrodes

Fig. 13 shows a flexible ablating element 74, which includes multiple, electrode elements, designated E1, E2, and E3 arranged in a spaced apart, segmented relationship along a flexible catheter body 76. The electrode elements can comprise generally rigid electrode rings, or spirally wound lengths of wire (as Fig. 13 shows), or electrode material coated upon the body 76.

As Fig. 13 shows, each electrode element

E1, E2, and E3 carries at least one and, preferably, at least two, temperature sensing elements, designated S1 to S6. When the electrode elements exceed about 10 mm in length (as Fig. 13 contemplates), the temperature sensing elements S1 to S6 are preferably located at the edges of electrode elements E1 to E3, where the electrode elements abut the underlying, non-electrically-conductive catheter body 76. These sensing elements S1 to S6 are positioned to sense the temperature of the electrode elements.

The sensing elements S1 to S6 can be secured to the electrode elements in various ways. For example, they can be secured to the inside surface of the electrode elements, or sandwiched between the inside surface of the electrode and the underlying flexible body.

Alternatively, the sensing elements S1 to S6 can be threaded up through the windings in the electrode elements to lay upon its exterior surface.

Regardless of the particulars, the sensing elements S1 to S6 are electrically insulated from the electrode elements, such as, for example, being encapsulated in an epoxy or PTFE coating, as described before.

As Fig. 13 also shows, additional temperature sensing elements S7 and S8 are preferably located between adjacent electrode elements E1 to E3. These temperature sensing elements S7 and S8 are positioned to sense tissue temperature between the electrode elements.

In this arrangement, each sensing element S7 and S8 is threaded through the flexible body between adjacent electrode segments E1 to E3. When the sensing element 80 comprises a thermocouple, an

epoxy material, such as Master Bond Polymer System EP32HT (Master Bond Inc., Hackensack, New Jersey), encapsulates the thermocouple junction, while also securing it to the flexible body. Alternatively, the thermocouple junction can be coated in a thin layer of polytetrafluoroethylene (PTFE) material. When used in thicknesses of less than about 0.002 inch, these materials have the sufficient insulating properties to electrically insulate the thermocouple junction from the associated electrode segment E1 to E3. The use of such materials typically will not be necessary when thermistors are used, because conventional thermistors are already encapsulated in an electrically insulating and thermally conducting material.

Further details of such multiple electrode structures are disclosed in copending U.S. Application Serial No. 08/286,930, filed August 8, 1994, entitled "Systems and Methods for Controlling Tissue Ablation Using Multiple Temperature Sensing Elements" and its continuation-in-part application Serial No. 08/439,824, filed May 12, 1995, entitled "Systems and Methods for Controlling Tissue Ablation Using Multiple Temperature Sensing Elements."

In this embodiment, the temperature acquisition system 64 is coupled to all temperature sensing elements S1 to S8. The system 64 continuously samples at prescribed time periods, t , the analog signals generated by all the sensing elements S1 to S8 based upon locally sensed temperature conditions. The system 64 converts the separate analog signals of the sensing elements S1 to S8 into individual, proportional digital signals. The digital signals from sensing elements S7 and S8 located between adjacent electrode elements

approximate inter-electrode tissue temperatures $T_{n,1}(t)$, where n identifies a particular one of the sensing elements S7 or S8. The digital signals from sensing elements S1 to S6 located on the electrode elements E1 to E3 correspond to electrode temperatures $T_{k,2}(t)$, where k identifies a particular one of the sensing elements S1 to S6.

In this embodiment, the temperature processing element 66 is coupled to the temperature acquisition system 64 to receive as input the digital signal temperatures $T_{n,1}(t)$ and electrode temperatures $T_{k,2}(t)$. The processing element 66 applies prescribed criteria to these actual temperature signals to derive, for the sampled time interval, a prediction of the hottest tissue temperature contacting each electrode element $T_{m,pred}(t)$, where m identifies a particular electrode element.

Fig. 17 shows, in schematic form, a representative system 200 for applying ablating energy by multiple electrodes based, at least in part, upon local temperature conditions sensed by multiple sensing elements.

In Fig. 17, the multiple sensing elements comprise thermocouples 208, 209, and 210 individually associated with multiple electrodes 201, 202, and 203. It should be appreciated that more thermocouples could also be associated with each electrode (as Fig. 13 shows), and/or thermocouples can be located between electrodes (as Fig. 13 also shows). The system 200 also includes a common reference thermocouple 211 carried within the coupler element 211 for exposure to the blood pool. The common reference thermocouple 211 could also be located externally, for example, in a catheter

handle or in the generator, if maintained there at a known temperature. Alternatively, other kinds of temperature sensing elements can be used, like, for example, thermistors, fluoro optic sensors, and resistive temperature sensors, in which case the reference sensor 211 would typically not be required.

The system 200 further includes an indifferent electrode 219 for operation in a uni-polar mode.

The system 200 includes a source 217 of ablating energy. In Fig. 17, the source 217 generates radio frequency (RF) energy. The source 217 is connected (through a conventional isolated output stage 216) to an array of power switches 214, one for each electrode region 201, 202, and 203. A connector 212 (carried by the probe handle) electrically couples each electrode region 201, 203, 203 to its own power switch 214 and to other parts of the system 200.

The system 200 also includes a microcontroller 231 coupled via an interface 230 to each power switch 214. The microcontroller 231 turns a given power switch 214 on or off to deliver RF power from the source 217 individually to the electrode regions 201, 202, and 203. The delivered RF energy flows from the respective electrode region 201, 202, and 203, through tissue, to the indifferent electrode 219, which is connected to the return path of the isolated output stage 216.

The power switch 214 and interface 230 configuration can vary according to the type of ablating energy being applied. Fig. 18 shows a representative implementation for applying RF ablating energy.

In this implementation, each power switch 214 includes an N-MOS power transistor 235 and a P-MOS power transistor 236 coupled in between the respective electrode region 201, 202, and 203 and the isolated output stage 216 of the power source 217.

A diode 233 conveys the positive phase of RF ablating energy to the electrode region. A diode 234 conveys the negative phase of the RF ablating energy to the electrode region. Resistors 237 and 238 bias the N-MOS and P-MOS power transistors 235 and 236 in conventional fashion.

The interface 230 for each power switch 214 includes two NPN transistors 239 and 240. The emitter of the NPN transistor 239 is coupled to the gate of the N-MOS power transistor 235. The collector of the NPN transistor 240 is coupled to the gate of the P-MOS power transistor 280.

The interface for each power switch 214 also includes a control bus 243 coupled to the microcontroller 231. The control bus 243 connects each power switch 214 to digital ground (DGND) of the microcontroller 231. The control bus 243 also includes a (+) power line (+5V) connected to the collector of the NPN transistor 239 and a (-) power line (-5V) connected to the emitter of the NPN interface transistor 240.

The control bus 243 for each power switch 214 further includes an E_{SEL} line. The base of the NPN transistor 239 is coupled to the E_{SEL} line of the control bus 243. The base of the NPN transistor 240 is also coupled to the E_{SEL} line of the control bus 243 via the Zener diode 241 and a resistor 232. E_{SEL} line connects to the cathode of the Zener diode 241 through the resistor 232. The Zener diode 241 is

selected so that the NPN transistor 240 turns on when E_{SEL} exceeds about 3 volts (which, for the particular embodiment shown, is logic 1).

5 It should be appreciated that the interface 230 can be designed to handle other logic level standards. In the particular embodiment, it is designed to handle conventional TTL (transistor transfer logic) levels.

10 The microcontroller 231 sets E_{SEL} of the control bus 243 either at logic 1 or at logic 0. At logic 1, the gate of the N-MOS transistor 235 is connected to (+) 5 volt line through the NPN transistors 239. Similarly, the gate of the P-MOS transistor 236 is connected to the (-) 5 volt line
15 through the NPN transistor 240. This conditions the power transistors 235 and 236 to conduct RF voltage from the source 217 to the associated electrode region. The power switch 214 is "on."

20 When the microcontroller 231 sets E_{SEL} at logic 0, no current flows through the NPN transistors 239 and 240. This conditions the power transistors 235 and 236 to block the conduction of RF voltage to the associated electrode region. The power switch 214 is "off."

25 The system 200 (see Fig. 17) further includes two analog multiplexers (MUX) 224 and 225. The multiplexers 224 and 225 receive voltage input from each thermocouple 208, 209, 210, and 211. The microcontroller 231 controls both multiplexers 224
30 and 225 to select voltage inputs from the multiple temperature sensing thermocouples 208, 209, 210, and 211.

35 The voltage inputs from the thermocouples 208, 209, 210, and 211 are sent to front end signal conditioning electronics. The inputs are amplified

by differential amplifier 226, which reads the voltage differences between the copper wires of the thermocouples 208/209/210 and the reference thermocouple 211. The voltage differences are
 5 conditioned by element 227 and converted to digital codes by the analog-to-digital converter 228. The look-up table 229 converts the digital codes to temperature codes.

10 In one preferred implementation, the microcontroller 316 operates the power switch interface 230 to deliver RF power from the source 217 in multiple pulses of duty cycle $1/N$, where N is the number of electrode segments.

15 With pulsed power delivery, the amount of power ($P_{E(J)}$) conveyed to each individual electrode region $E(J)$ is expressed as follows:

$$P_{E(J)} \sim AMP_{E(J)}^2 \times DUTYCYCLE_{E(J)}$$

where:

$AMP_{E(J)}$ is the amplitude of the RF voltage conveyed to the electrode region $E(J)$, and

20 $DUTYCYCLE_{E(J)}$ is the duty cycle of the pulse, expressed as follows:

$$DUTYCYCLE_{E(J)} = \frac{TON_{E(J)}}{TON_{E(J)} + TOFF_{E(J)}}$$

where:

$TON_{E(J)}$ is the time that the electrode region $E(J)$ emits energy during each pulse period,

25 $TOFF_{E(J)}$ is the time that the electrode region $E(J)$ does not emit energy during each pulse period.

The expression $TON_{E(J)} + TOFF_{E(J)}$ represents the period of the pulse for each electrode region

E(J).

5 In this mode, the microcontroller 231 collectively establishes duty cycle ($DUTYCYCLE_{E(J)}$) of $1/N$ for each electrode region (N being equal to the number of electrode regions).

10 The microcontroller 231 may sequence successive power pulses to adjacent electrode regions so that the end of the duty cycle for the preceding pulse overlaps slightly with the beginning of the duty cycle for the next pulse. This overlap in pulse duty cycles assures that the source 217 applies power continuously, with no periods of interruption caused by open circuits during pulse switching between successive electrode regions.

15 In this mode, the microcontroller 231 cycles in successive data acquisition sample periods. During each sample period, the microcontroller 231 selects individual sensors $S(J,K)$, and voltage differences are read by the predictor 290 (through MUX 225) and converted to temperature codes T_{PRED} , which are transmitted to the controller 215.

25 The predictor 290 receives the temperature codes. In the preferred implementation, when there are multiple temperature sensing elements on a given electrode element, the predictor selects as $T_{k,2}$ the hottest of the electrode temperatures sensed by the sensing elements on the electrode element. Also, when the electrode element is bounded by both side by a tissue temperature sensing element, the controller predictor also selects as $T_{n,1}$ the hottest of the tissue temperatures sensed by adjacent tissue sensing elements.

30 Using the selected values of $T_{n,1}(t)$ and $T_{k,2}(t)$, the predictor derives $T_{m,PRED}(t)$ in any of the

manners above described for each electrode element.

In this mode, the controller 215 compares the predicted temperature T_{PRED} for each electrode during each data acquisition period to a set point temperature T_{SET} . Based upon this comparison, the controller 215 varies the amplitude $\text{AMP}_{\text{E(J)}}$ of the RF voltage delivered to the electrode region, while the microcontroller 231 maintains the $\text{DUTYCYCLE}_{\text{E(J)}}$ for that electrode region and all other electrode regions, to establish and maintain T_{PRED} at the set point temperature T_{SET} .

The manner in which the controller 215 governs $\text{AMP}_{\text{E(J)}}$ can incorporate proportional control methods, proportional integral derivative (PID) control methods, or fuzzy logic control methods.

B. Self-Heated Temperature Sensing Element

Fig.14 shows another alternative embodiment of an electrode 78 with multiple temperature sensing elements 80 and 82. In Fig. 14, both temperature sensing elements 80 and 82 are connected by soldering or by thermally conducting adhesive to the thermal mass of the electrode 78.

Alternatively (as Fig. 15 shows), the sensing element 80 can be located to sense tissue temperature, as sensing element 30 in Fig. 4.

In addition a resistance heating element 84 is provided for the purpose of heating the thermal mass of the electrode 78. In the illustrated embodiment shown in Fig. 14, the heating element 84 extends in intimate contact about the metal steering spring 52. As the heating spring 52 heats up, the heat is conducted to the thermal mass of the electrode 78.

Alternatively (as Fig. 15 shows), the

heating element 84 can be wrapped about a portion of the electrode 78 under the catheter body 22. In either embodiment, the heating element 84 is located in good thermal conductive contact with the electrode for ohmic heating of the element 84 with DC energy to thereby heat the electrode 78 by conductive heat transfer.

The heating element 84 can comprise an insulated constant wire having a high resistance, or Nichrome or insulated toaster wire having the same characteristic. As Fig. 15 shows, the heating wire 84 is mated with low resistance copper wire 85 close to the electrode 78. The copper wire 85 extends the rest of the way through the catheter body 22.

The distance (Δx in Fig. 15) between the two sensing elements 80 and 82 should preferably be maximized to the fullest extent possible, given the size of the electrode 78. For example, for an 8F/4 mm electrode, Δx should be at least 3 mm.

Fig. 16 shows a system 400 including an electrode 402 having two temperature sensors TS_1 and TS_2 . The electrode 402 also includes the heating element HE 84 heated by the heater 404. The electrode 402 is coupled to the RF power source 406.

The temperatures read by TS_1 and TS_2 (T_1 and T_2) are acquired by the temperature acquisition system 408. The system 400 operates in two phases.

During this first phase, no ablating energy is directly applied to the electrode 402. HE is actuated by the heater 404 so that T_2 is kept about a set value T_{heat_set} . The temperature controller 410 which controls the heater 404 can use appropriate control techniques, such as PID, etc.

During this phase, the temperatures T_1 and

T_2 are acquired by the acquisition system 408. The electrical power generated by the heater 404 is also measured, P_{heater} .

5 T_1 , T_2 and P_{heater} are inputted to a processing system 412, which, based upon the distance Δx between temperature sensing elements TS_1 and TS_2 and the whether TS_1 is sensing electrode or tissue temperature, computes the heat loss, Q_{loss} , and the temperature spatial gradient $\Delta T/\Delta x$. The processing system 412 can acquire information concerning the electrode configuration from the physician, or by a read-only-memory chip and the equivalent associated with the electrode which the processing system 412 can interrogate. The heat loss, Q_{loss} , will depend on the thermal conductivity, density and heat capacity of the metal of the electrode 402, the amount of electrical and thermal contact between tissue and electrode, and the convective cooling induced by the blood flow. 10 Therefore, Q_{loss} and $\Delta T/\Delta x$ are indications of the present status of the electrical-thermal system at the tissue-electrode-blood interface. This status information is later used to predict and control the tissue temperature during ablation in the second phase. 15 20 25

In the second phase, ablation energy is applied to tissue through the electrode 402. The values of T_1 , T_2 , Q_{loss} , $\Delta T/\Delta x$, $T_{\text{heat_set}}$, and P_{heater} are fed as inputs to a predictor 414.

30 The predictor 414 includes in look-up table form relationships among T_1 , T_2 , Q_{loss} , $\Delta T/\Delta x$, $T_{\text{heat_set}}$, P_{heater} , and T_{PRED} . The inputs to the table are T_1 , T_2 , Q_{loss} , $\Delta T/\Delta x$, $T_{\text{heat_set}}$, P_{heater} , and the output of the table is T_{PRED} . The look-up table is constructed based on experimental data acquired with an apparatus 35

similar to that shown in Fig. 6, using an electrode like that shown in Figs. 14 and 15. The table correlates experimentally measured T_1 , T_2 , Q_{loss} , $\Delta T/\Delta x$, $T_{\text{heat_set}}$, P_{heater} to experimentally measured maximum tissue temperature. The output T_{PRED} of the look-up table is best-fitted to the experimental data.

The values of Q_{loss} , $\Delta T/\Delta x$, $T_{\text{heat_set}}$, P_{heater} taken during the first phase in connection with T_1 and T_2 characterize the system for input to the table. The current status of T_1 and T_2 taken during the second phase provide from the table a unique output predicting the maximal tissue temperature.

The predictor 414 outputs the predicted tissue temperature T_{PRED} . T_{PRED} and a set temperature value $T_{\text{ABL_set}}$ are fed as inputs to a controller 416, which controls the RF power source 406. The controller 416 controls predicted tissue temperature about $T_{\text{ABL_set}}$.

The illustrated and preferred embodiments envision the use of micro-processor controlled components using digital processing to analyze information and generate feedback signals. It should be appreciated that other logic control circuits using micro-switches, AND/OR gates, invertors, and the like are equivalent to the micro-processor controlled components and techniques shown in the preferred embodiments. It should also be appreciated that the algorithms disclosed in this Specification lend themselves to implementation using either digital or analog devices.

Various features of the invention are set forth in the claims that follow.

WE CLAIM:

1. An apparatus for heating tissue comprising
 - an electrode to transmit heating energy to a tissue region,
 - 5 a first sensing element associated with the electrode for measuring a first temperature,
 - a second sensing element associated with the electrode for measuring a second temperature, and
 - 10 a processing element to process one or more temperatures measured by the first and second sensing elements and to derive therefrom a prediction of maximum temperature of the tissue region.
2. An apparatus for supplying energy to an electrode for ablating tissue comprising
 - a generator adapted to be coupled to an electrode to supply energy to the electrode for ablating tissue,
 - 5 a controller coupled to the generator to supply power to the generator, the controller comprising
 - a first sensing element for measuring
 - 10 temperature of the electrode,
 - a second sensing element for measuring temperature of tissue contacting the electrode, and
 - a processing element to process one or more temperatures measured by the first and second
 - 15 sensing elements and to derive therefrom a prediction of maximum temperature of the tissue region and for generating a signal to control power supplied to the generator based, at least in part, upon the maximum tissue temperature prediction.
3. An apparatus for ablating body tissue

comprising

an electrode for contacting a tissue region
to transmit ablation energy,

5 a first sensing element for measuring
temperature of the electrode,

a second sensing element for measuring
temperature of tissue contacting the electrode, and

10 a processing element to process one or more
temperatures measured by the first and second
sensing elements and to derive therefrom a
prediction of maximum temperature of the tissue
region.

4. An apparatus according to claim 1 or
2 or 3

5 wherein the processing element generates an
output based upon the maximum tissue temperature
prediction.

5. An apparatus according to claim 4
wherein the processing element generates
the output based upon comparing the maximum tissue
temperature prediction to a prescribed temperature.

6. An apparatus according to claim 5
wherein the prescribed temperature remains
essentially constant over time.

7. An apparatus according to claim 5
wherein the prescribed temperature changes
at least once as a function of time.

8. An apparatus according to claim 1 or
2 or 5 or 6 or 7

5 wherein the processing element applies at
least one proportional, derivative, or integral
coefficient to the comparison of the maximum tissue
temperature prediction to the prescribed temperature
to generate the output.

9. An apparatus according to claim 1 or

2 or 3

5 wherein the processing element controls the transmission of ablation energy by the electrode based, at least in part, upon the maximum tissue temperature prediction.

10. An apparatus according to claim 9
5 wherein the processing element controls the transmission of ablation energy based upon comparing the maximum tissue temperature prediction to a prescribed temperature.

11. An apparatus according to claim 10
wherein the prescribed temperature remains essentially constant over time.

12. An apparatus according to claim 10
wherein the prescribed temperature changes at least once as a function of time.

13. An apparatus according to claim 10 or
11 or 12
5 wherein the processing element applies at least one proportional, derivative, or integral coefficient to the comparison of the maximum tissue temperature prediction to the prescribed temperature to control the transmission of ablation energy.

14. An apparatus according to claim 1 or
2 or 3 or 4 or 9
wherein the electrode transmits radio frequency energy.

15. An apparatus according to claim 1 or
2 or 3 or 4 or 9
wherein the processing element includes a neural network predictor.

16. An apparatus according to claim 1 or
2 or 3 or 4 or 9
wherein the processing element derives the maximum tissue temperature prediction based, at

5 least in part, upon fuzzy logic.

17. An apparatus according to claim 1 or
2 or 3

5 wherein the processing element processes
changes in temperatures measured by the first and
second sensing elements over time to derive the
maximum tissue temperature prediction.

18. An apparatus according to claim 1 or
2 or 3 or 4 or 9

5 wherein the processing element derives the
maximum tissue temperature prediction based, at
least in part, upon an analytical function $f(T_1,$
 $T_2)$, where T_1 is temperature measured by the first
sensing element and T_2 is temperature measured by the
second sensing element.

19. An apparatus according to claim 1 or
2 or 3

wherein the electrode carries at least one
of the first and second sensing elements.

20. An apparatus according to claim 19

wherein the at least one sensing element is
carried within the electrode.

21. An apparatus according to claim 1 or
2 or 3

5 wherein the second sensing element is
carried by the electrode within a carrier in thermal
conductive contact with tissue.

22. An apparatus according to claim 21

5 wherein the carrier is made from a thermal
conducting material having a high thermal
conductivity that is at least 1.0 watt (W) per meter
(m) Kelvin (K), or 1.0 W/m K.

23. An apparatus according to claim 1 or
2 or 3

and further including a second electrode

5 spaced along a body from the first mentioned electrode, and

wherein the second sensing element is located on the body between the first and second electrodes.

24. An apparatus according to claim 23 and further including a third temperature sensing element to measure temperature of the second electrode.

25. An apparatus for transmitting energy to an electrode for heating tissue comprising
5 a generator adapted to be coupled to an electrode to supply energy to the electrode for heating tissue,

a controller coupled to the generator to supply power to the generator, the controller comprising

10 a first sensing element associated with the electrode for measuring a first temperature,

a second sensing element associated with the electrode for measuring a second temperature, and

15 a processing element to process one or more temperatures measured by the first and second sensing elements and to derive therefrom a prediction of maximum temperature of the tissue region and for generating a signal to control power
20 supplied to the generator based, at least in part, upon the maximum tissue temperature prediction.

26. An apparatus according to claim 1 or 2 or 25

5 wherein the processing element controls the transmission of heating energy by the electrode based, at least in part, upon the maximum tissue

temperature prediction.

27. An apparatus according to claim 26
wherein the processing element controls the
transmission of heating energy based upon comparing
the maximum tissue temperature prediction to a
prescribed temperature.

28. An apparatus according to claim 27
wherein the prescribed temperature remains
essentially constant over time.

29. An apparatus according to claim 27
wherein the prescribed temperature changes
at least once as a function of time.

30. An apparatus according to claim 27 or
28 or 29

wherein the processing element applies at
least one proportional, derivative, or integral
coefficient to the comparison of the maximum tissue
temperature prediction to the prescribed temperature
to control the transmission of heating energy.

31. An apparatus according to claim 1 or
2 or 25

wherein the electrode carries at least one
of the first and second sensing elements.

32. An apparatus according to claim 31
wherein the at least one sensing element is
carried within the electrode.

33. An apparatus according to claim 1 or
2 or 25

wherein at least one of the sensing
elements is in thermal conductive contact with
tissue.

34. An apparatus according to claim 1 or
2 or 25

wherein none of the sensing elements is in
thermal conductive contact with tissue.

35. An apparatus according to claim 1 or
2 or 25

wherein at least one of the sensing
elements is in thermal conductive contact with the
5 electrode.

36. An apparatus according to claim 1 or
2 or 25

wherein at least one of the sensing
elements is carried by the electrode within a
5 carrier in thermal conductive contact with tissue.

37. An apparatus according to claim 1 or
2 or 25

wherein the carrier is made from a thermal
conducting material having a high thermal
5 conductivity that is at least 1.0 watt (W) per meter
(m) Kelvin (K), or 1.0 W/m K.

38. An apparatus according to claim 1 or
2 or 25

and further including a second electrode
spaced along a body from the first mentioned
5 electrode, and

wherein the at least one of the sensing
elements is located on the body between the first
and second electrodes.

39. An apparatus according to claim 38

and further including a third temperature
sensing element associated with the second electrode
to measure a third temperature, and

5 wherein the processing element derives the
maximum tissue temperature prediction from one or
more temperatures measured by the first, second, and
third sensing elements.

40. A method for heating body tissue
comprising

positioning an electrode to transmit heat

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energy to a tissue region,

5 measuring a first temperature using a
temperature sensing element associated with the
electrode,

 measuring a second temperature using a
temperature sensing element associated with the
10 electrode, and

 processing at least one of the first and
second temperatures to derive a prediction of
maximum temperature of the tissue region.

41. A method according to claim 40
and further including the step of
generating an output based upon the maximum tissue
temperature prediction.

42. A method according to claim 40
wherein the output is based upon comparing
the maximum tissue temperature prediction to a
prescribed temperature.

43. A method according to claim 41
wherein the prescribed temperature remains
essentially constant over time.

44. A method according to claim 41
wherein the prescribed temperature changes
at least once as a function of time.

45. An electrode able to transmit heating
energy comprising

 a first sensing element associated with the
electrode for measuring a first temperature,
5 a second sensing element associated with
the electrode for measuring a second temperature,
 a heating element in thermal conductive
contact with the electrode for heating the
electrode.

46. An electrode for contacting a tissue
region to transmit ablation energy,

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5 a first sensing element carried by the
electrode for measuring temperature of the
electrode,

 a second sensing element carried by the
electrode for measuring either temperature of the
electrode or temperature of tissue contacting the
electrode, and

10 a heating element in thermal conductive
contact with the electrode for heating the
electrode.

47. An electrode according to claim 45 or
46

 wherein the electrode transmits radio
frequency energy.

48. An electrode according to claim 45 or
46

 wherein the second sensing element is
carried by the electrode within a carrier in thermal
conductive contact with tissue.

49. An electrode according to claim 48

5 wherein the carrier is made from a thermal
conducting material having a high thermal
conductivity that is at least 1.0 watt (W) per meter
(m) Kelvin (K), or 1.0 W/m K.

50. An electrode according to claim 45 or
46

 wherein the heating element is heated by
ohmic heating.

51. An electrode according to claim 45 or
46

 wherein the heating element comprises a
coil of wire wrapped in thermal conductive contact
with the element.

52. An electrode according to claim 45 or
46

- 45 -

wherein the heating element comprises wire coupled in thermal conductive contact with the electrode.

53. An apparatus for heating tissue comprising

an electrode able to transmit heating energy from a source,

5 a first sensing element associated with the electrode for measuring a first temperature,

a second sensing element associated with the electrode for measuring a second temperature,

10 a heating element, separate from the source, in thermal conductive contact with the electrode for heating the electrode, the heating element being operable in an ON mode and an OFF mode, and

15 a processing element to process one or more temperatures measured by the first and second sensing elements with the heating element in the ON mode and while the electrode transmits heating energy from the source with the heating element in the OFF mode and to derive therefrom a prediction of
20 maximum temperature of the tissue region.

54. An apparatus according to claim 53

5 wherein the processing element derives the maximum tissue temperature prediction, at least in part, by computing heat loss and temperature spatial gradient for the electrode while being heated by the heating element and while transmitting heating energy.

55. An apparatus according to claim 53

wherein the processing element generates an output based upon the maximum tissue temperature prediction.

56. An apparatus according to claim 55

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wherein the processing element generates the output based upon comparing the maximum tissue temperature prediction to a prescribed temperature.

57. An apparatus according to claim 56 wherein the prescribed temperature remains essentially constant over time.

58. An apparatus according to claim 56 wherein the prescribed temperature changes at least once as a function of time.

59. An apparatus according to claim 56 or 57 or 58

5 wherein the processing element applies at least one proportional, derivative, or integral coefficient to the comparison of the maximum tissue temperature prediction to the prescribed temperature to generate the output.

60. An apparatus according to claim 53 wherein the processing element controls the transmission of heating energy by the electrode based, at least in part, upon the maximum tissue temperature prediction.

5 61. An apparatus according to claim 60 wherein the processing element controls the transmission of heating energy based upon comparing the maximum tissue temperature prediction to a prescribed temperature.

62. An apparatus according to claim 61 wherein the prescribed temperature remains essentially constant over time.

63. An apparatus according to claim 61 wherein the prescribed temperature changes at least once as a function of time.

64. An apparatus according to claim 61 or 62 or 63

wherein the processing element applies at

- 47 -

5 least one proportional, derivative, or integral coefficient to the comparison of the maximum tissue temperature prediction to the prescribed temperature to control the transmission of ablation energy.

65. An apparatus according to claim 53 wherein the electrode transmits radio frequency energy.

66. An apparatus according to claim 53 wherein the processing element derives the maximum tissue temperature prediction based, at least in part, upon an analytical function.

67. An apparatus for supplying energy to an electrode for ablating tissue comprising
5 a generator adapted to be coupled to an electrode to supply energy to the electrode for ablating tissue,

a controller coupled to the generator to supply power to the generator, the controller comprising
10 a first sensing element for measuring temperature of the electrode,

a second sensing element for measuring either temperature of tissue contacting the electrode or of the electrode,

15 a heating element in thermal conductive contact with the electrode for heating the electrode, the heating element being operable in an ON mode and an OFF mode, and

a processing element to process one or more temperatures measured by the first and second
20 sensing elements with the heating element in the ON mode and while the electrode transmits ablation energy with the heating element in the OFF mode and to derive therefrom a prediction of maximum temperature of the tissue region and for generating

- 48 -

25 a signal to control power supplied to the generator based, at least in part, upon the maximum tissue temperature prediction.

68. A method for heating body tissue comprising

transmitting heating energy from a source by the electrode,

5 heating the electrode with a heating element, separate from the source, and without transmitting heating energy,

measuring a first temperature with a first sensing element associated with the electrode ,

10 measuring a second temperature with a second sensing element associated with the electrode,

without heating the electrode with the heating element, transmitting heating energy from the source by the electrode,

15 measuring a third and fourth temperatures with the first and second temperature sensors, respectively, and

processing at least one of the first, 20 second, third, and fourth temperatures a prediction of maximum temperature of the tissue region.

69. A method for ablating body tissue comprising

5 placing an electrode in contact with a tissue region to transmit ablation energy with the electrode,

heating the electrode with a heating element and without transmitting ablation energy,

measuring a first temperature of the electrode,

10 measuring a second temperature either of tissue contacting the electrode or of the electrode,

- 49 -

without heating the electrode with the heating element, transmitting ablation energy with the electrode,

15 measuring a third temperature of the electrode,

 measuring a fourth temperature either of tissue contacting the electrode or of the electrode, and

20 deriving from at least one sample of the first, second, third, and fourth temperatures a prediction of maximum temperature of the tissue region.

70. An apparatus for supplying energy to an electrode for heating tissue comprising

 a generator adapted to be coupled to an electrode to supply energy to the electrode for heating tissue, and

5 a controller coupled to the generator to supply power to the generator, the controller comprising a processing element that maintains at the electrode a targeted temperature about a set temperature by generating a signal to decrease power supplied to the generator at a rate not larger than a prescribed rate while supplying heating energy to the electrode.

71. An apparatus for supplying energy to an electrode for ablating tissue comprising

 a generator adapted to be coupled to an electrode to supply energy to the electrode for ablating tissue, and

5 a controller coupled to the generator to supply power to the generator, the controller comprising a processing element that maintains at the electrode a targeted temperature about a set temperature by generating a signal to decrease

10

- 50 -

power supplied to the generator at a rate not greater than a prescribed rate while supplying ablation energy to the electrode.

72. A method of heating tissue comprising the steps of

supplying energy to an electrode to heat tissue, and

5 controlling power to the generator to maintain at the electrode a targeted temperature about a set temperature by generating a signal to decrease power supplied to the generator at a rate not larger than a prescribed rate while supplying
10 heating energy to the electrode.

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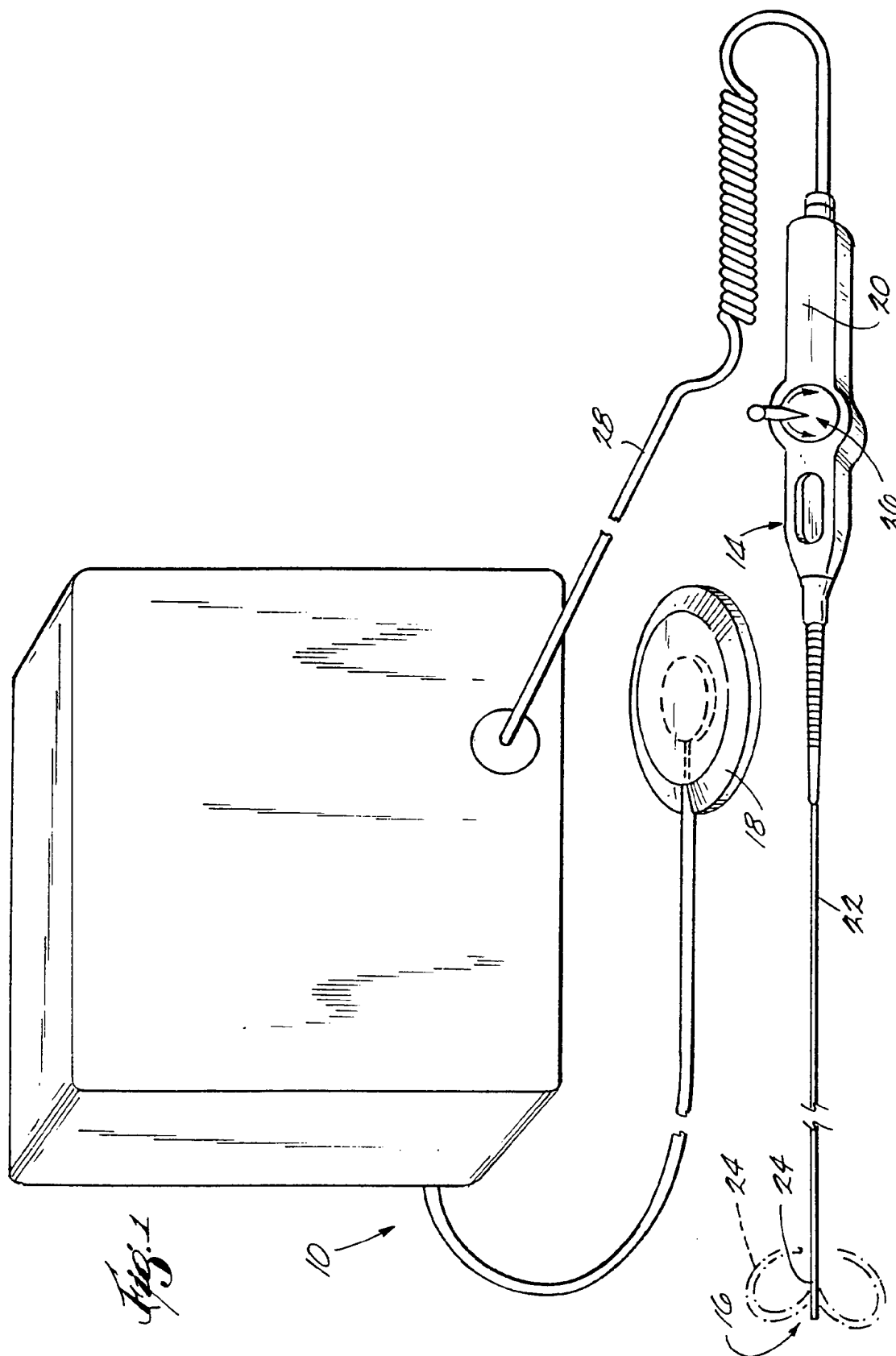


Fig. 3

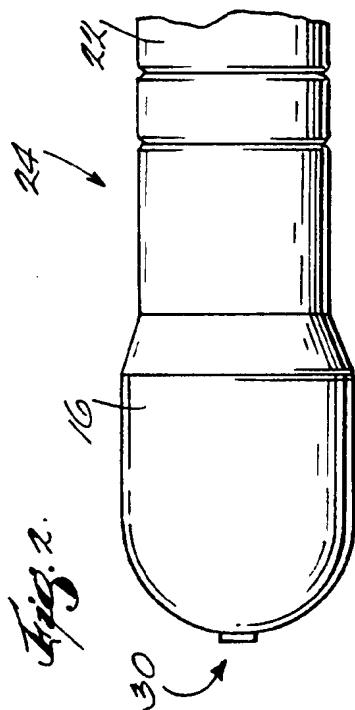
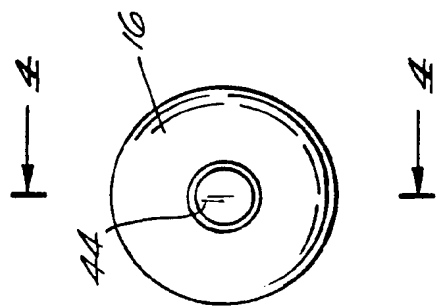
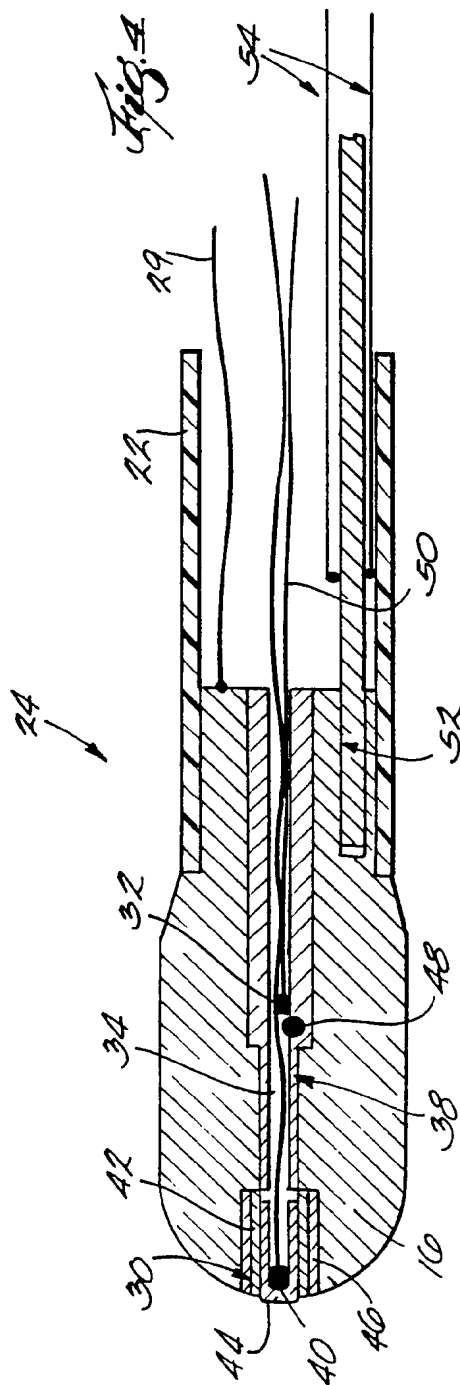


Fig. 4



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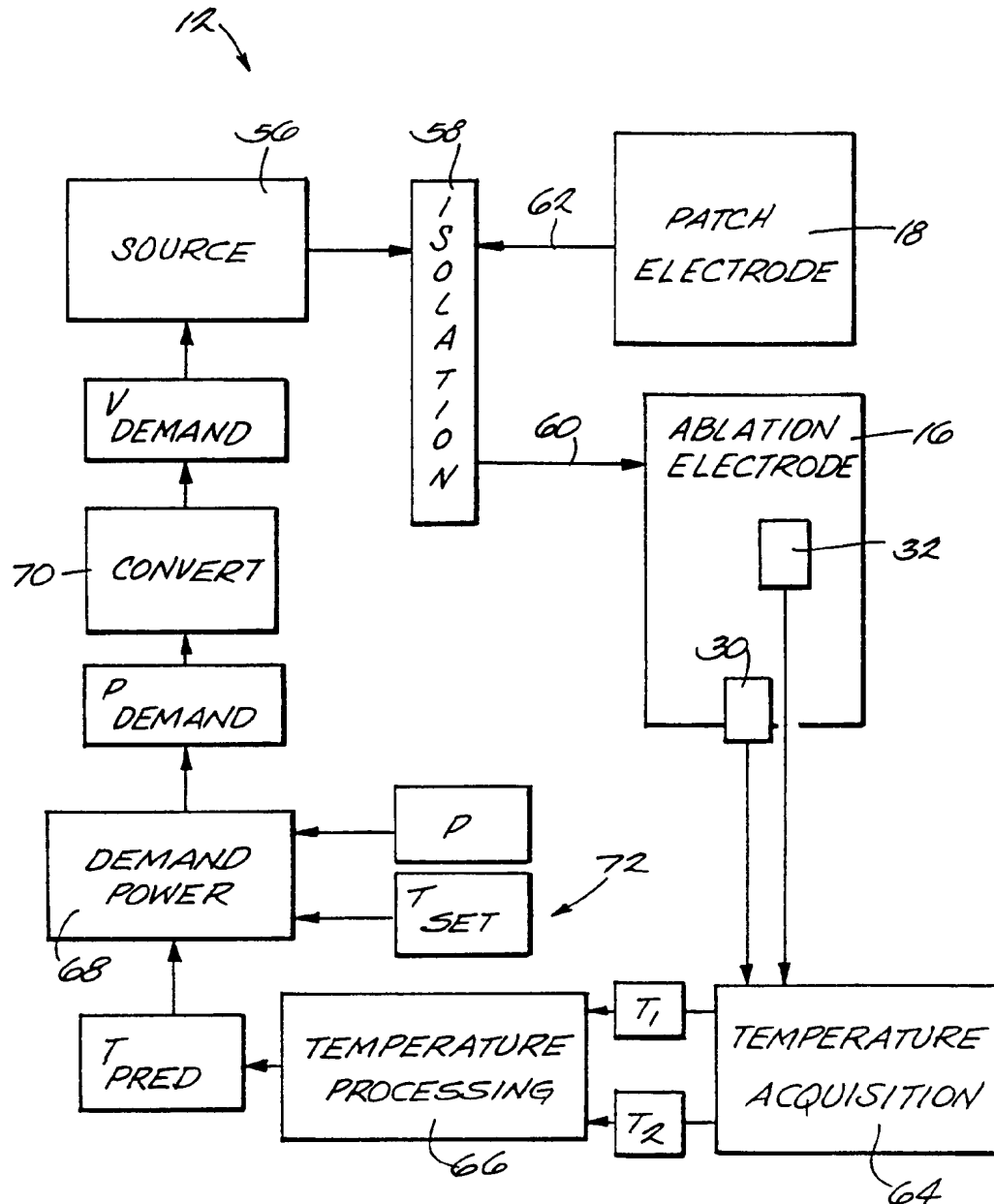
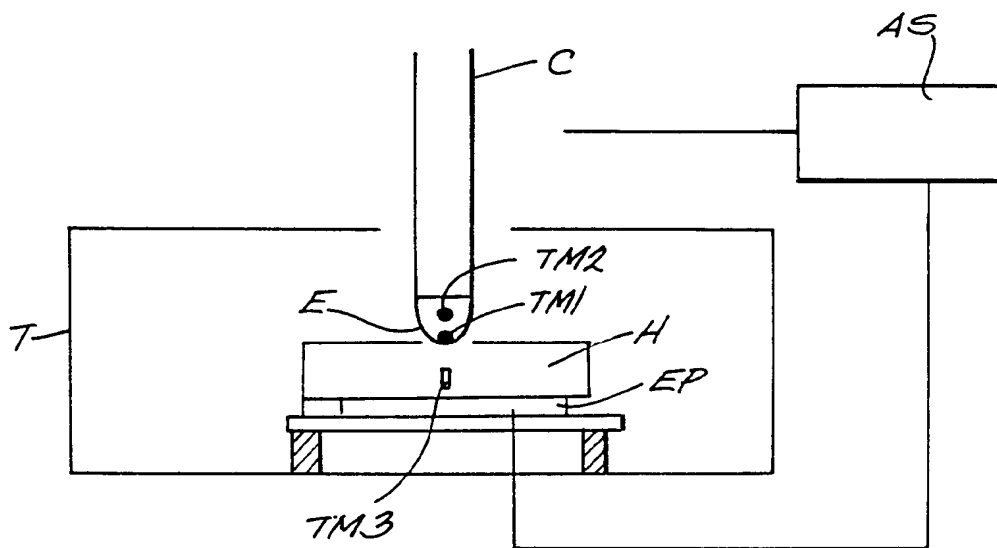
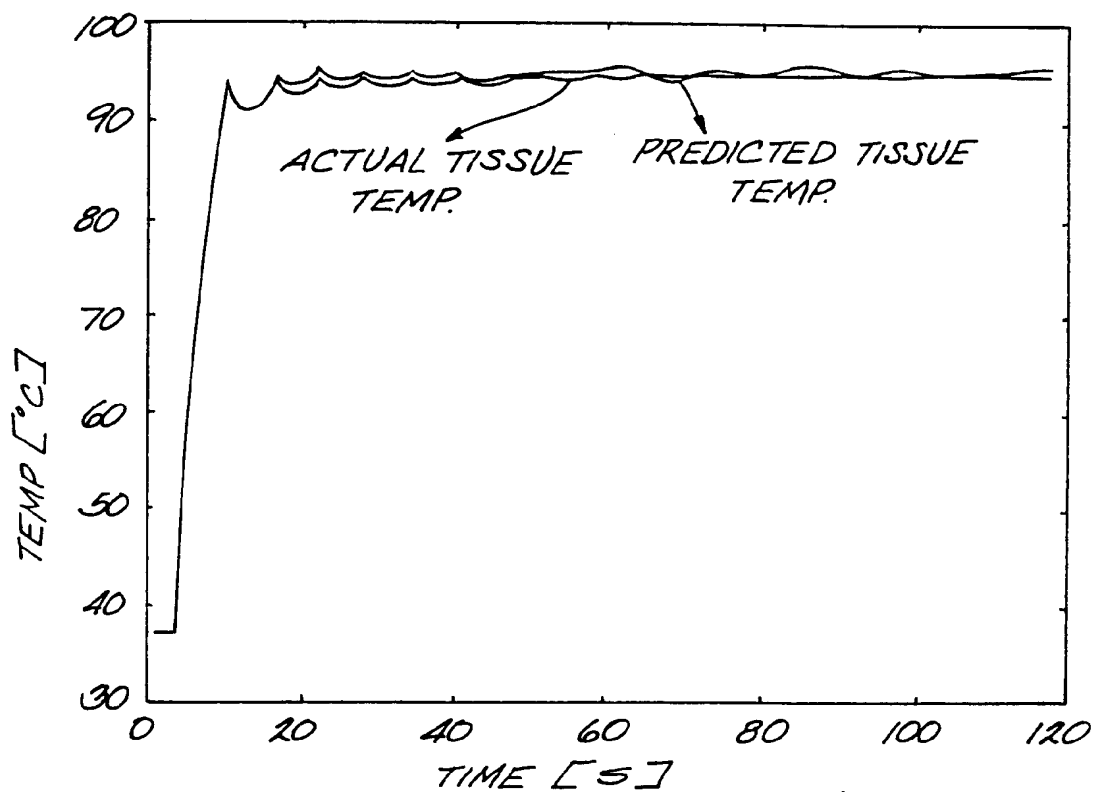
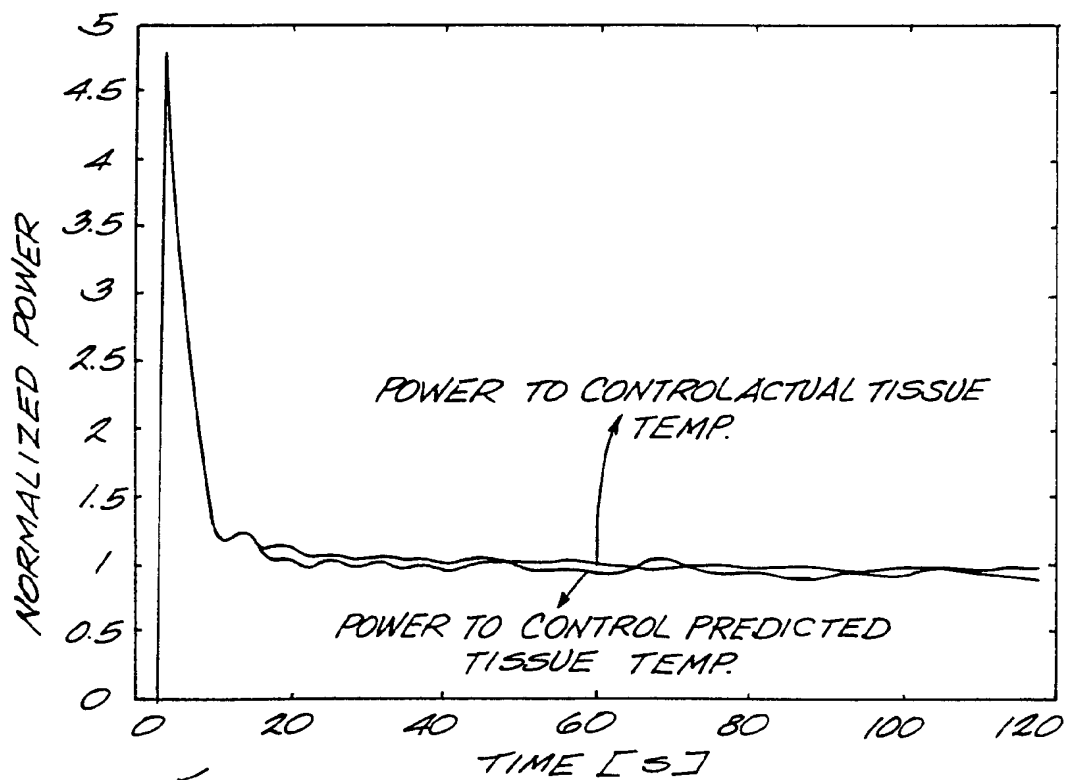


Fig. 5

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Fig. 6

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*Fig. 1A**Fig. 1B*

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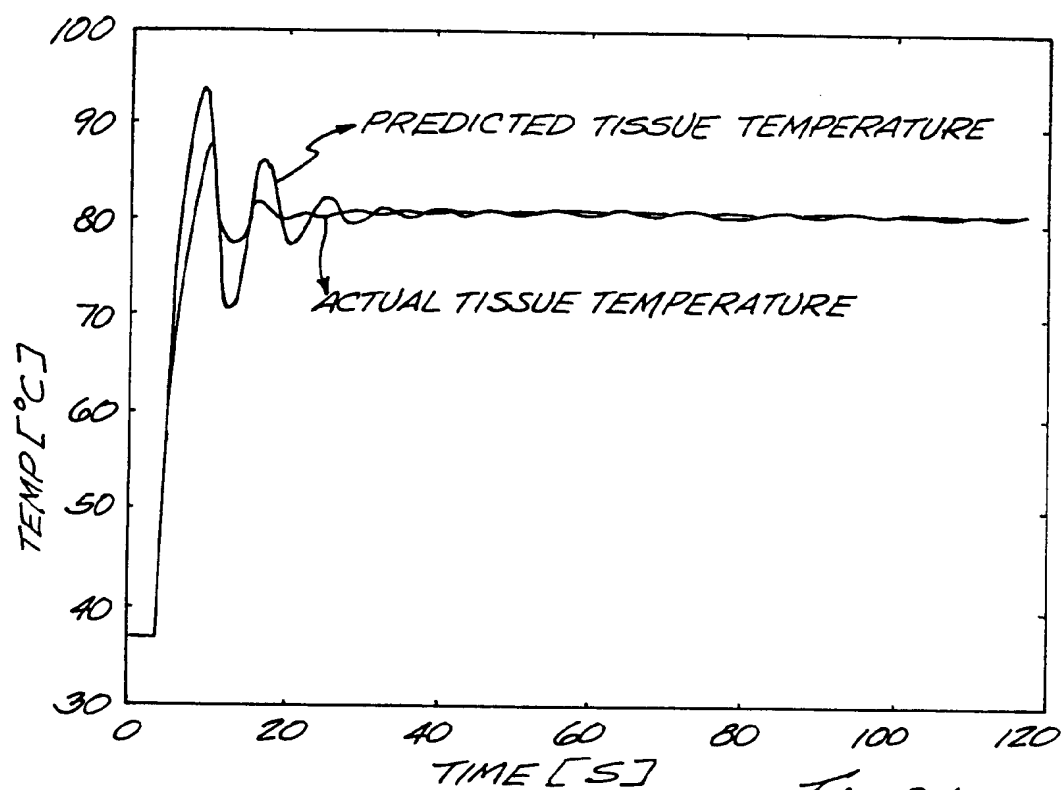


Fig. 8A

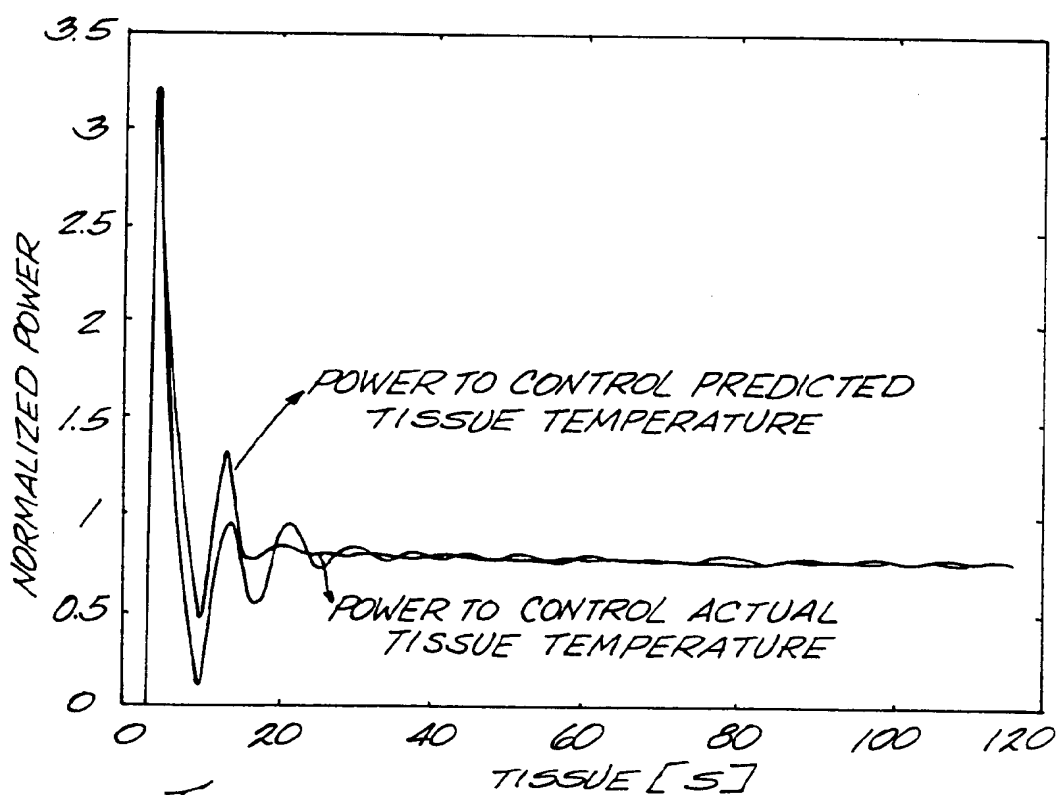
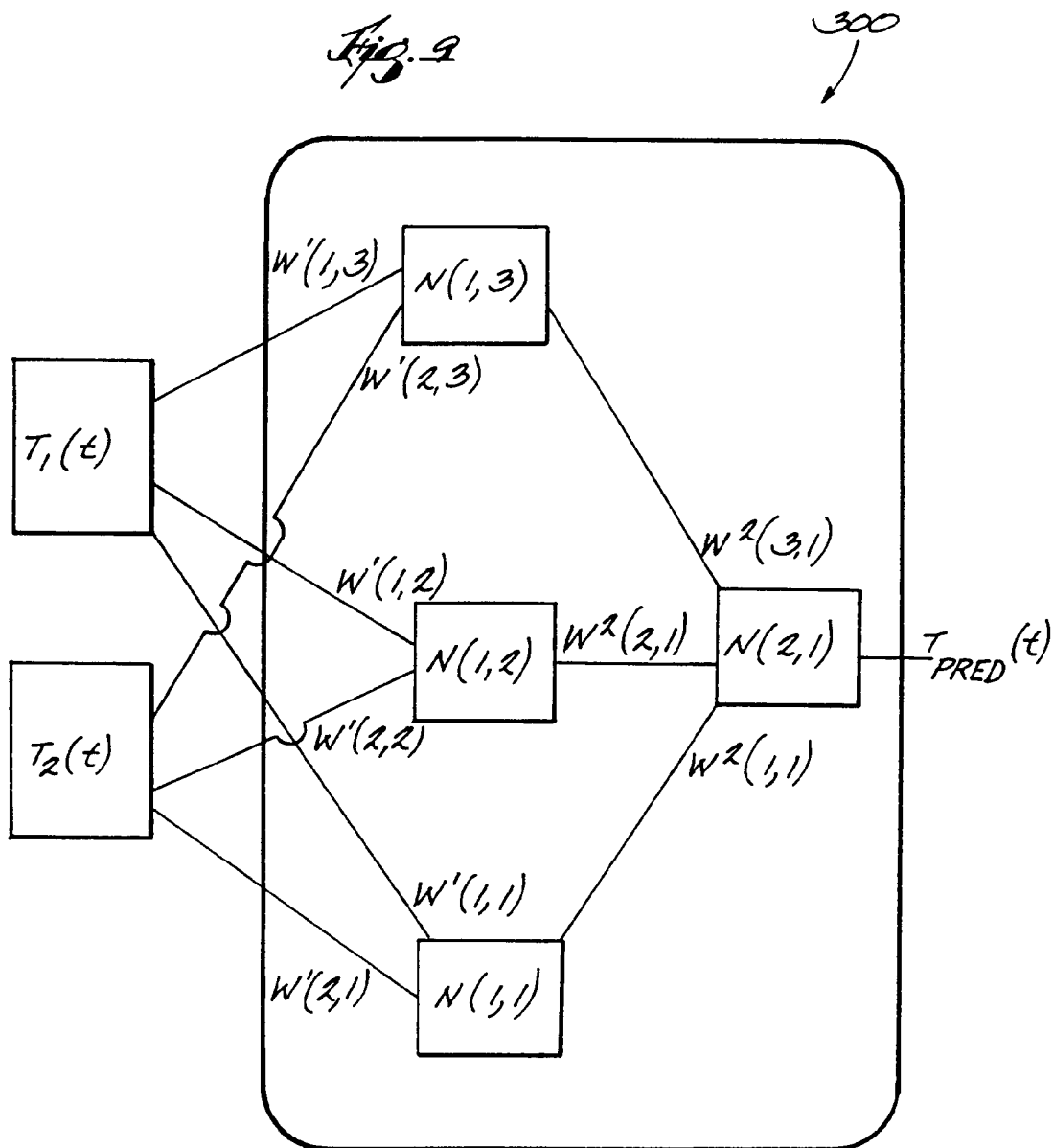
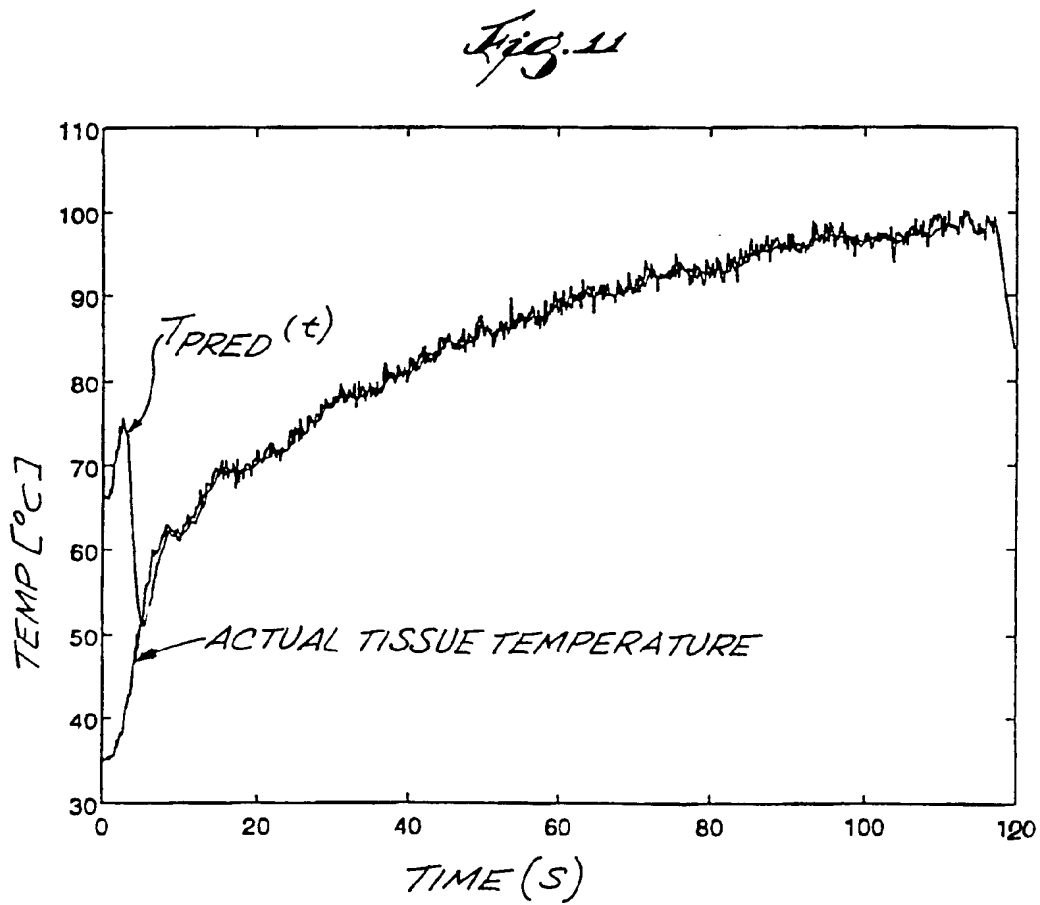
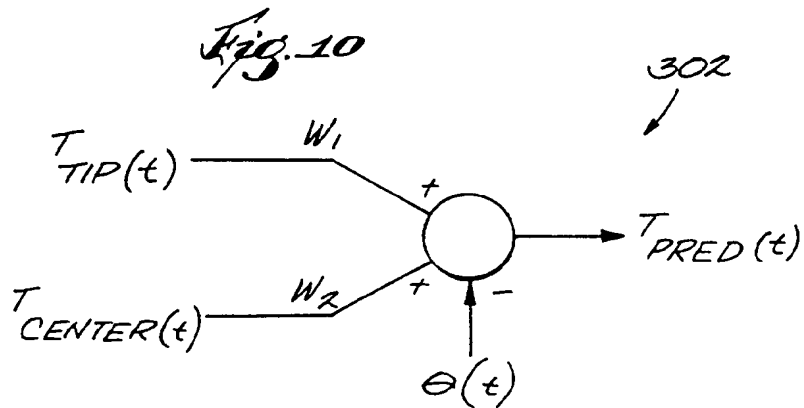


Fig. 8B

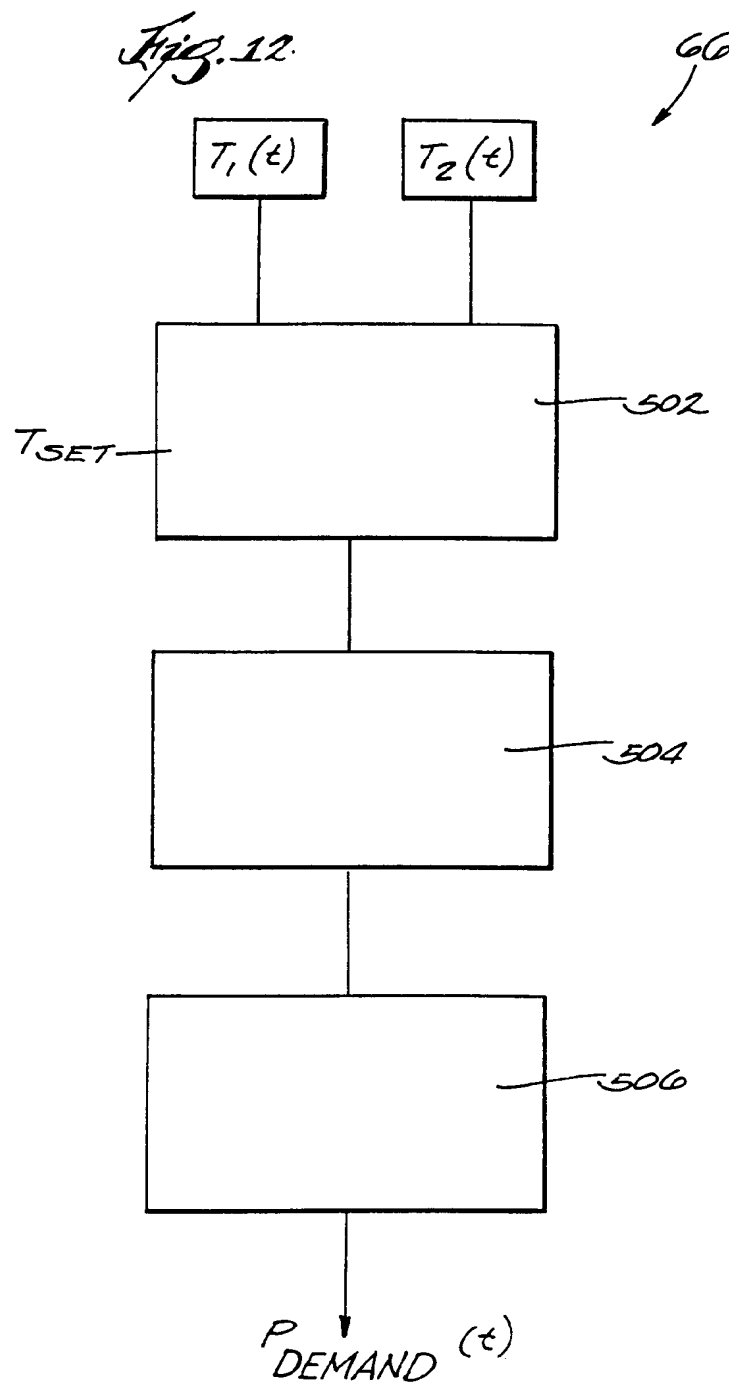
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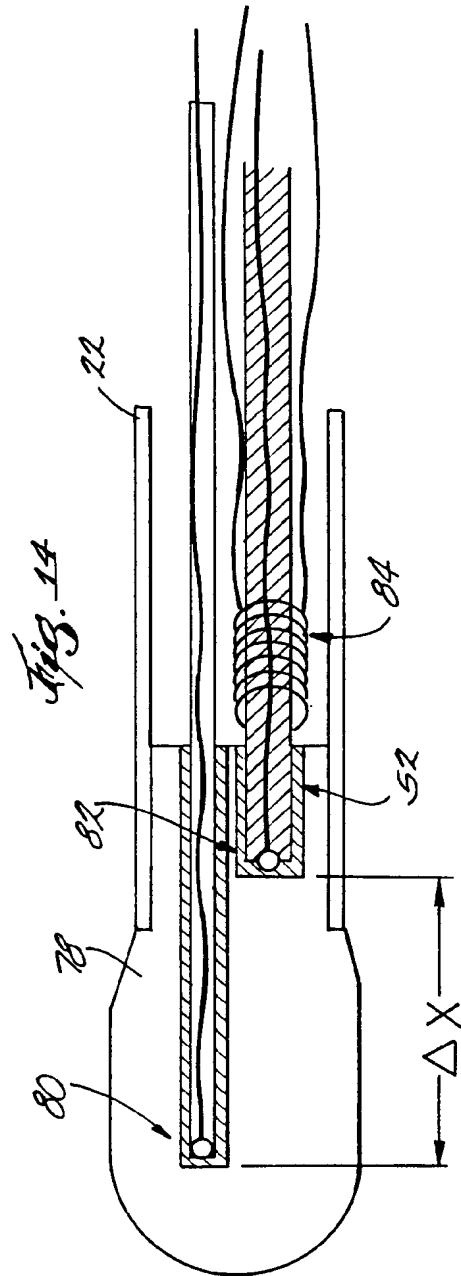
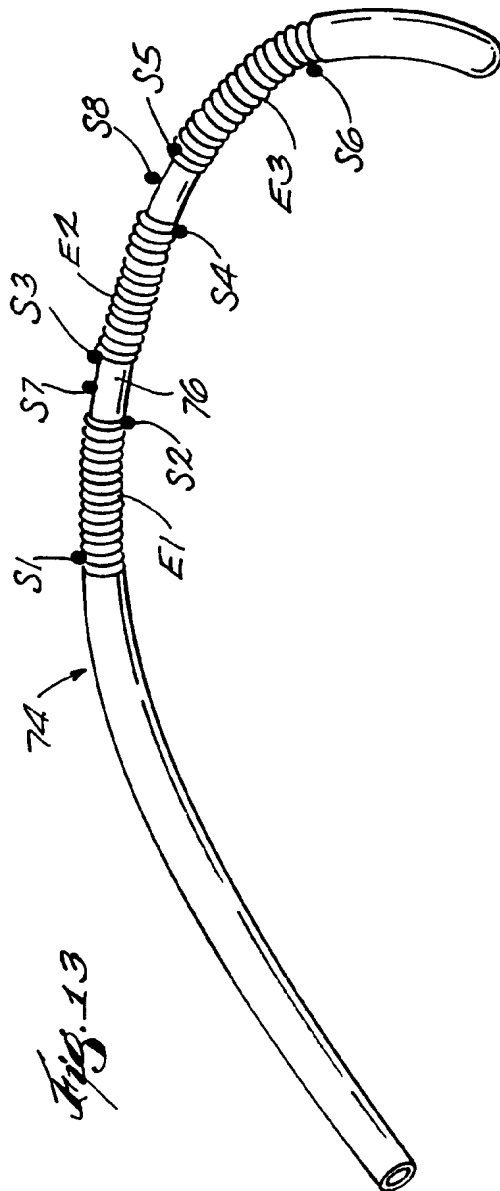


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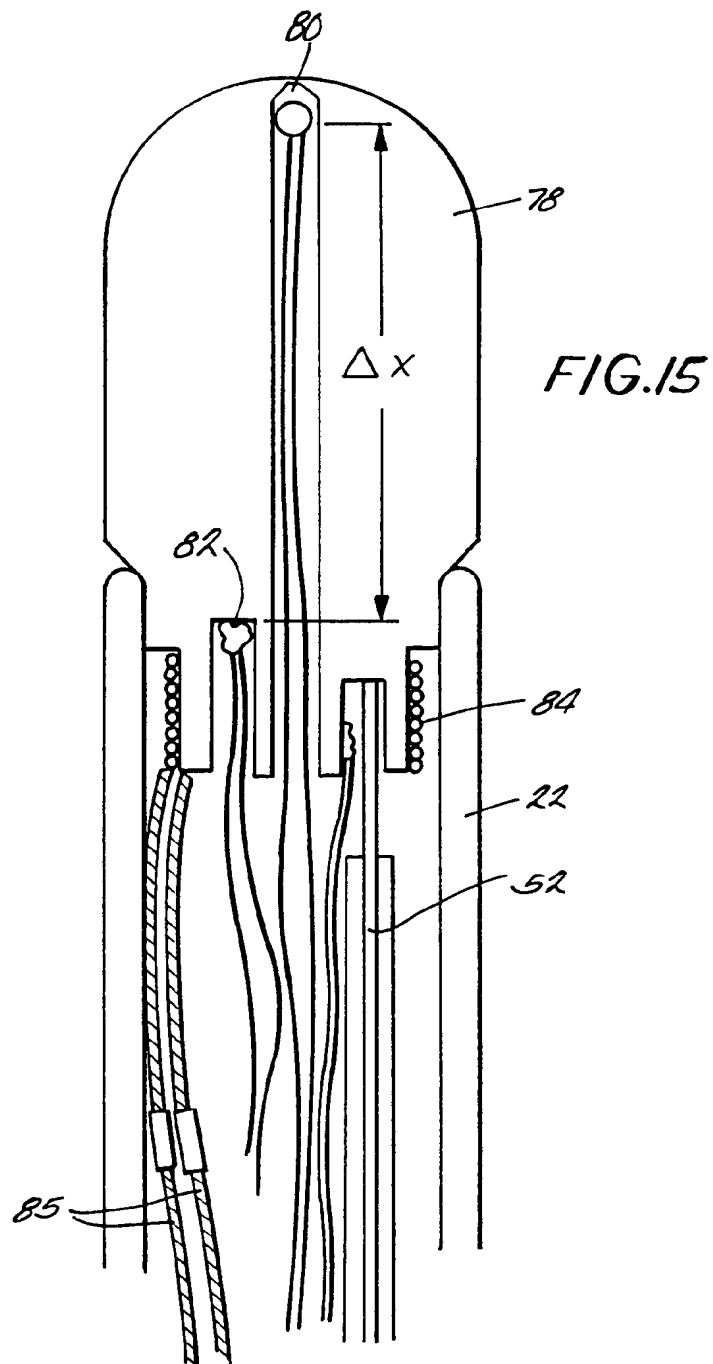


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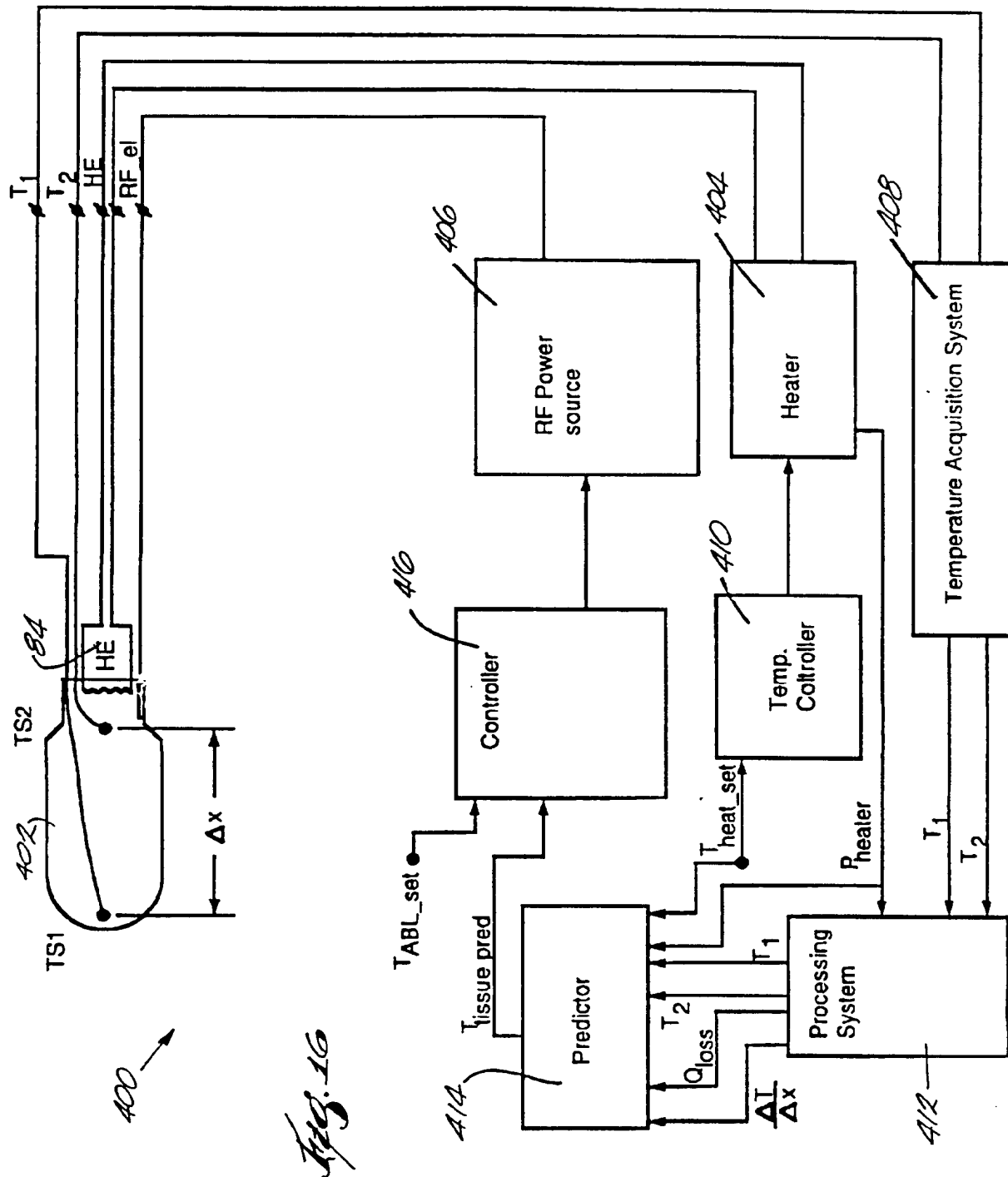


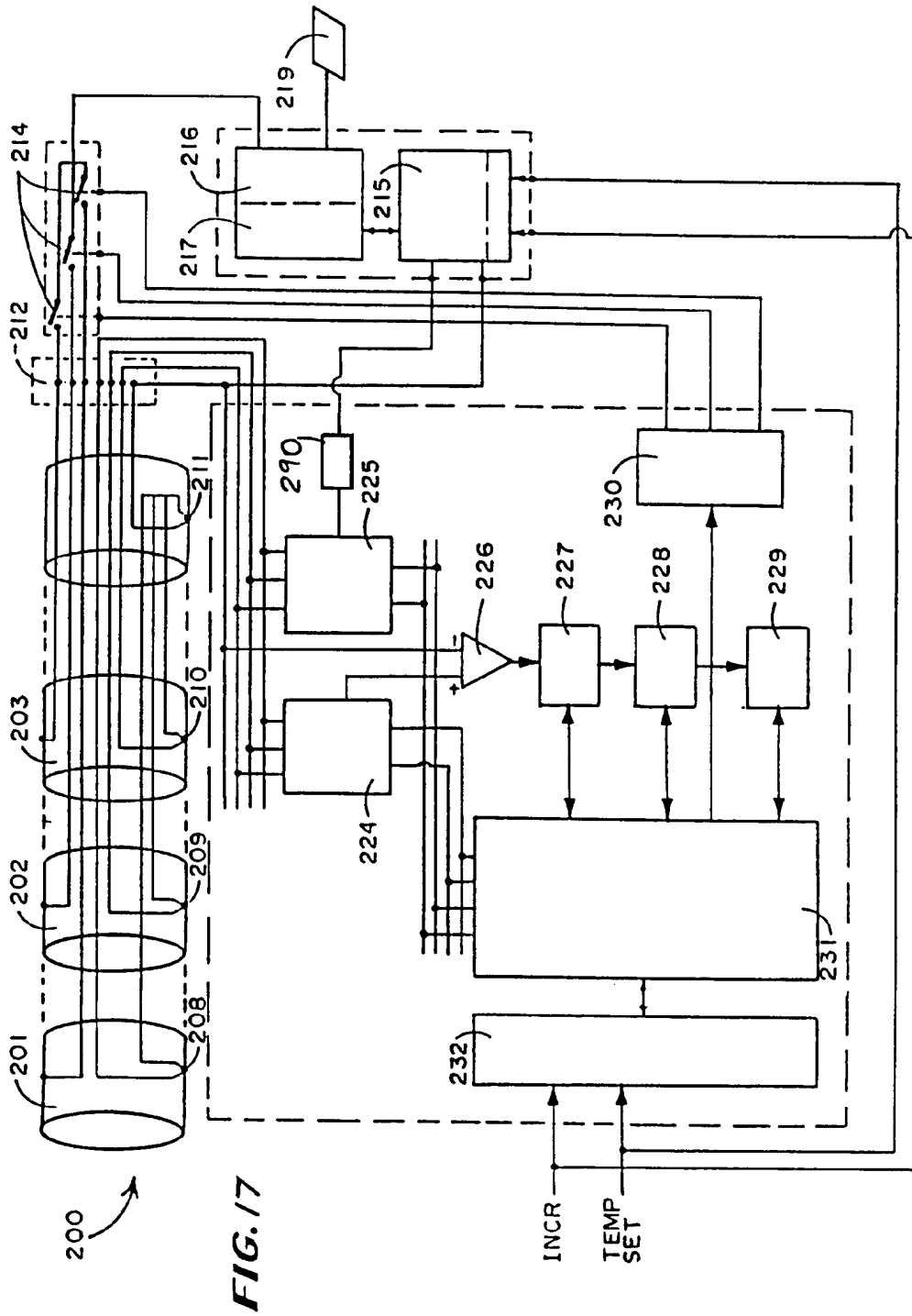


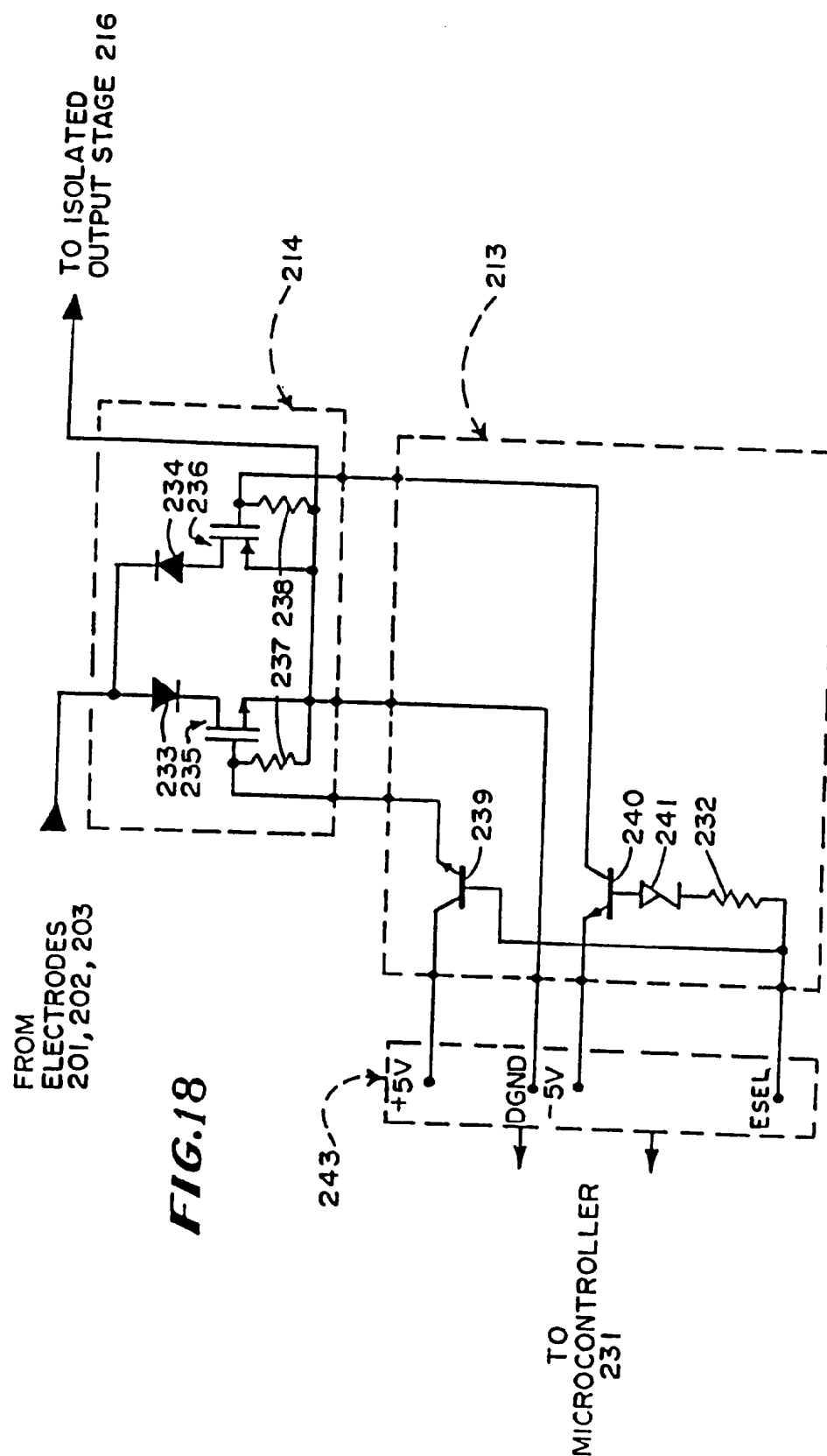
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INTERNATIONAL SEARCH REPORT

International application No.
PCT/US96/09598

A. CLASSIFICATION OF SUBJECT MATTER

IPC(6) : A61B 17/38; A61N 5/00

US CL : 606/28

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

U.S. : 128/642, 736; 606/27-32, 37-42, 45-52; 607/115, 116, 122

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X, Y	US, A, 4,907,589 (COSMAN) 13 March 1990, see entire document.	70-72
Y	US, A, 5,383,917 (DESAI ET AL.) 24 January 1995, see entire document.	70-72

☐ Further documents are listed in the continuation of Box C. ☐ See patent family annex.

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Date of the actual completion of the international search

09 SEPTEMBER 1996

Date of mailing of the international search report

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